

(19) World Intellectual Property Organization  
International Bureau



(43) International Publication Date  
12 July 2001 (12.07.2001)

PCT

(10) International Publication Number  
WO 01/50679 A2

(51) International Patent Classification<sup>7</sup>: H04L 12/00

(21) International Application Number: PCT/US00/33405

(22) International Filing Date: 7 December 2000 (07.12.2000)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:  
09/474,650 29 December 1999 (29.12.1999) US

(63) Related by continuation (CON) or continuation-in-part (CIP) to earlier application:  
US 09/474,650 (CON)  
Filed on 29 December 1999 (29.12.1999)

(71) Applicant (for all designated States except US): INTEL CORPORATION [US/US]; 2200 Mission College Boulevard, Santa Clara, CA 95052 (US).

(72) Inventors; and

(75) Inventors/Applicants (for US only): WOLRICH,

Gilbert [US/US]; 4 Cider Mill Road, Framingham, MA 01701 (US). BERNSTEIN, Debra [US/US]; 443 Peakham Road, Sudbury, MA 01776 (US). ADILETTA, Matthew, J. [US/US]; 20 Monticello Drive, Worcester, MA 01603 (US). HOOPER, Donald, F. [US/US]; 19 Main Circle, Shrewsbury, MA 01545 (US).

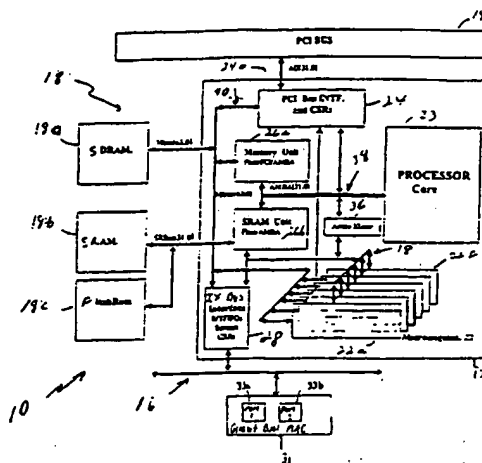
(74) Agent: HARRIS, Scott, C.; Fish & Richardson P.C., 4350 La Jolla Village Drive, Suite 500, San Diego, CA 92122 (US).

(81) Designated States (national): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, BZ, CA, CH, CN, CR, CU, CZ, DE, DK, DM, DZ, EE, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, SL, TJ, TM, TR, TT, TZ, UA, UG, US, UZ, VN, YU, ZA, ZW.

(84) Designated States (regional): ARIPO patent (GH, GM, KE, LS, MW, MZ, SD, SL, SZ, TZ, UG, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE, TR), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, GW, ML, MR, NE, SN, TD, TG).

[Continued on next page]

(54) Title: METHOD AND APPARATUS FOR GIGABIT PACKET ASSIGNMENT FOR MULTITHREADED PACKET PROCESSING



(57) Abstract: A network processor that has multiple processing elements, each supporting multiple simultaneous program threads with access to shared resources in an interface. Packet data is received from high-speed ports in segments and each segment is assigned to one of the program threads. Each packet may be assigned to a single program thread, two program threads - one for header segment processing and the other for handling payload segment(s) - or a different program thread for segment of data in a packet. Dedicated inputs for ready status and sequence numbers provide assistance needed for receiving the packet data over a high speed port. The dedicated inputs are used to monitor ready flags from the high speed ports on a cycle-by-cycle basis. The sequence numbers are used by the assigned threads to maintain ordering of segments within a packet, as well as to order the writes of the complete packets to transmit queues.



**Published:**

— Without international search report and to be republished upon receipt of that report.

*For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.*

METHOD AND APPARATUS FOR GIGABIT PACKET ASSIGNMENT FOR  
MULTITHREADED PACKET PROCESSING

Background of the Invention

5

The invention relates generally to network data processing.

Networking products such as routers require high speed components for packet data movement, i.e., collecting  
10 packet data from incoming network device ports and queuing the packet data for transfer to appropriate forwarding device ports. They also require high-speed special controllers for processing the packet data, that is, parsing the data and making forwarding decisions. Because  
15 the implementation of these high-speed functions usually involves the development of ASIC or custom devices, such networking products are of limited flexibility and thus tend to be quite rigid in their assignment of ports to the high-speed controllers. Typically, each controller is  
20 assigned to service network packets from for one or more given ports on a permanent basis.

### Summary of the Invention

In one aspect of the invention, forwarding data includes associating control information with data received from a first port and using the associated control information to enqueue the data for transmission to a second port in the same order in which the data was received from the first port.

10

### Brief Description of the Drawings

Other features and advantages of the invention will be apparent from the following description taken together with the drawings in which:

15       FIG. 1 is a block diagram of a communication system employing a hardware-based multi-threaded processor;

      FIG. 2 is a block diagram of a microengine employed in the hardware-based multi-threaded processor of FIG. 1;

      FIG. 3 is an illustration of an exemplary thread  
20 task assignment;

      FIG. 4 is a block diagram of an I/O bus interface shown in FIG. 1;

      FIG. 5 is a detailed diagram of a bus interface unit

employed by the I/O bus interface of FIG. 4;

FIGS. 6A-6F are illustrations of various bus configuration control and status registers (CSRs);

FIG. 7 is a detailed diagram illustrating the  
5 interconnection between two Gigabit Ethernet ("fast") ports and the bus interface unit;

FIGS. 8A-8C are illustrations of the formats of the RCV\_RDY\_CTL, RCV\_RDY\_HI and RCV\_RDY\_LO CSR registers, respectively;

10 FIG. 9 is a depiction of the receive threads and their interaction with the I/O bus interface during a receive process;

FIGS. 10A and 10B are illustrations of the format of the RCV\_REQ FIFO and the RCV\_CTL FIFO, respectively;

15 FIGS. 11A-11B are illustrations of the formats of the SOP\_SEQx registers and ENQUEUE\_SEQx registers, respectively;

FIG. 12 is a flow diagram of the receive process for fast ports;

20 FIGS. 13A and 13B are flow diagrams which illustrate portions of the receive process for fast ports using a single thread mode;

FIGS. 14A and 14B are flow diagrams which illustrate

portions of the receive process for fast ports using a dual thread (or header/body) mode;

FIGS. 15A and 15B are flow diagrams which illustrate portions of the receive process for fast ports using an explicit (distributed thread) mode; and

FIG. 16 is a flow diagram of a packet enqueueing process for fast ports.

#### Detailed Description

10

Referring to FIG. 1, a communication system 10 includes a parallel, hardware-based multi-threaded processor 12. The hardware based multi-threaded processor 12 is coupled to a first peripheral bus (shown as a PCI bus) 14, a second peripheral bus referred to as an I/O bus 16 and a memory system 18. The system 10 is especially useful for tasks that can be broken into parallel subtasks or functions. The hardware-based multi-threaded processor 12 includes multiple microengines 22, each with multiple hardware controlled program threads that can be simultaneously active and independently work on a task. In the embodiment shown, there are six microengines 22a-22f and each of the six microengines is capable of processing

four program threads, as will be described more fully below.

The hardware-based multi-threaded processor 12 also includes a processor 23 that assists in loading microcode control for other resources of the hardware-based multi-threaded processor 12 and performs other general purpose computer type functions such as handling protocols, exceptions, extra support for packet processing where the microengines pass the packets off for more detailed processing. In one embodiment, the processor 23 is a StrongARM (ARM is a trademark of ARM Limited, United Kingdom) core based architecture. The processor (or core) 23 has an operating system through which the processor 23 can call functions to operate on the microengines 22a-22f.

The processor 23 can use any supported operating system, preferably real-time operating system. For the core processor implemented as a StrongARM architecture, operating systems such as MicrosoftNT real-time, VXWorks and :CUS, a freeware operating system available over the Internet, can be used.

The six microengines 22a-22f each operate with shared resources including the memory system 18, a PCI bus interface 24 and an I/O bus interface 28. The PCI bus

interface provides an interface to the PCI bus 14. The I/O bus interface 28 is responsible for controlling and interfacing the processor 12 to the I/O bus 16. The memory system 18 includes a Synchronous Dynamic Random Access Memory (SDRAM) 18a, which is accessed via an SDRAM controller 26a, a Static Random Access Memory (SRAM) 18b, which is accessed using an SRAM controller 26b, and a nonvolatile memory (shown as a FlashROM) 18c that is used for boot operations. The SDRAM 18a and SDRAM controller 26a are typically used for processing large volumes of data, e.g., processing of payloads from network packets. The SRAM 18b and SRAM controller 26b are used in a networking implementation for low latency, fast access tasks, e.g., accessing look-up tables, memory for the processor 23, and so forth. The microengines 22a-22f can execute memory reference instructions to either the SDRAM controller 26a or the SRAM controller 18b.

The hardware-based multi-threaded processor 12 interfaces to network devices such as a media access controller device, including a high-speed (or fast) device 31, such as Gigabit Ethernet MAC, ATM device or the like, over the I/O bus 16. In the embodiment shown, the high-speed device is a Dual Gigabit MAC device having two fast



ports 33a, 33b. Each of the network devices attached to the I/O bus 16 can include a plurality of ports to be serviced by the processor 12. Other devices, such as a host computer (not shown), that may be coupled to the PCI bus 14 are also serviced by the processor 12. In general, as a network processor, the processor 12 can interface to any type of communication device or interface that receives/sends large amounts of data. The processor 12 functioning as a network processor could receive units of packet data from the device 31 and process those units of packet data in a parallel manner, as will be described. The unit of packet data could include an entire network packet (e.g., Ethernet packet) or a portion of such a packet.

Each of the functional units of the processor 12 are coupled to one or more internal buses. The internal buses include an internal core bus 34 (labeled "AMBA") for coupling the processor 23 to the memory controllers 26a, 26b and to an AMBA translator 36. The processor 12 also includes a private bus 38 that couples the microengines 22a-22f to the SRAM controller 26b, AMBA translator 36 and the Fbus interface 28. A memory bus 40 couples the memory controllers 26a, 26b to the bus interfaces 24, 28 and the

memory system 18.

Referring to FIG. 3, an exemplary one of the microengines 22a-22f is shown. The microengine 22a includes a control store 70 for storing a microprogram.

5 The microprogram is loadable by the central processor 20. The microengine 70 also includes control logic 72. The control logic 72 includes an instruction decoder 73 and program counter units 72a-72d. The four program counters are maintained in hardware. The microengine 22a also

10 includes context event switching logic 74. The context event switching logic 74 receives messages (e.g., SEQ\_#\_EVENT\_RESPONSE; FBI\_EVENT\_RESPONSE; SRAM\_EVENT\_RESPONSE; SDRAM\_EVENT\_RESPONSE; and AMBA\_EVENT\_RESPONSE) from each one of the share resources,

15 e.g., SRAM 26b, SDRAM 26a, or processor core 20, control and status registers, and so forth. These messages provides information on whether a requested function has completed. Based on whether or not the function requested by a thread has completed and signaled completion, the

20 thread needs to wait for that complete signal, and if the thread is enable to operate, then the thread is place on an available thread list (not shown). As earlier mentioned, the microengine 22a can have a maximum of 4 threads of

execution available.

In addition to event signals that are local to an executing thread, the microengine employs signaling states that are global. With signaling states, an executing  
5 thread can broadcast a signal state to all microengines 22.

Any and all threads in the microengines can branch on these signaling states. These signaling states can be used to determine availability of a resource or whether a resource is due for servicing.

10 The context event logic 74 has arbitration for the four threads. In one embodiment, the arbitration is a round robin mechanism. However, other arbitration techniques, such as priority queuing or weighted fair queuing, could be used. The microengine 22a also includes  
15 and execution box (EBOX) data path 76 that includes an arithmetic logic unit (ALU) 76a and a general purpose register (GPR) set 76b. The ALU 76a performs arithmetic and logical functions as well as shift functions.

The microengine 22a further includes a write  
20 transfer registers file 78 and a read transfer registers file 80. The write transfer registers file 78 stores data to be written to a resource. The read transfer registers file 80 is for storing return data from a resource.

Subsequent to or concurrent with the data arrival, an event signal from the respective shared resource, e.g., memory controllers 26a, 26b, or core 23, will be provided to the context event arbiter 74, which in turn alerts the thread  
5 that the data is available or has been sent. Both transfer register files 78, 80 are connected to the EBOX 76 through a data path. In the described implementation, each of the register files includes 64 registers.

The functionality of the microengine threads is  
10 determined by microcode loaded (via the core processor) for a particular user's application into each microengine's control store 70. Referring to FIG. 3, an exemplary thread task assignment 90 is shown. Typically, one of the microengine threads is assigned to serve as a receive  
15 scheduler 92 and another as a transmit scheduler 94. A plurality of threads are configured as receive processing threads 96 and transmit processing (or "fill") threads 98. Other thread task assignments include a transmit arbiter 100 and one or more core communication threads 102. Once  
20 launched, a thread performs its function independently.

The receive scheduler thread 92 assigns packets to receive processing threads 96. In a packet forwarding application for a bridge/router, for example, the receive

processing thread parses packet headers and performs lookups based in the packet header information. Once the receive processing thread or threads 96 has processed the packet, it either sends the packet as an exception to be further processed by the core 23 (e.g., the forwarding information cannot be located in lookup and the core processor must learn it), or stores the packet in the SDRAM and queues the packet in a transmit queue by placing a packet link descriptor for it in a transmit queue associated with the transmit (forwarding port) indicated by the header/lookup. The transmit queue is stored in the SRAM. The transmit arbiter thread 100 prioritizes the transmit queues and the transmit scheduler thread 94 assigns packets to transmit processing threads that send the packet out onto the forwarding port indicated by the header/lookup information during the receive processing.

The receive processing threads 96 may be dedicated to servicing particular ports or may be assigned to ports dynamically by the receive scheduler thread 92. For certain system configurations, a dedicated assignment may be desirable. For example, if the number of ports is equal to the number of receive processing threads 96, then it may be quite practical as well as efficient to assign the

receive processing threads to ports in a one-to-one, dedicated assignment. In other system configurations, a dynamic assignment may provide a more efficient use of system resources.

5           The receive scheduler thread 92 maintains scheduling information 104 in the GPRs 76b of the microengine within which it executes. The scheduling information 104 includes thread capabilities information 106, port-to-thread assignments (list) 108 and "thread busy" tracking  
10 information 110. At minimum, the thread capabilities information informs the receive scheduler thread as to the type of tasks for which the other threads are configured, e.g., which threads serve as receive processing threads. Additionally, it may inform the receive scheduler of other  
15 capabilities that may be appropriate to the servicing of a particular port. For instance, a receive processing thread may be configured to support a certain protocol, or a particular port or ports. A current list of the ports to which active receive processing threads have been assigned  
20 by the receive scheduler thread is maintained in the thread-to-port assignments list 108. The thread busy mask register 110 indicates which threads are actively servicing a port. The receive scheduler uses all of this scheduling

information in selecting threads to be assigned to ports that require service for available packet data, as will be described in further detail below.

Referring to FIG. 4, the I/O bus interface 28 includes shared resources 120, which are coupled to a push/pull engine interface 122 and a bus interface unit 124. The bus interface unit 124 includes a ready bus controller 126 connected to a ready bus 128 and an Fbus controller 130 for connecting to a portion of the I/O bus referred to as an Fbus 132. Collectively, the ready bus 128 and the Fbus 132 make up the signals of the I/O bus 16 (FIG. 1). The resources 120 include two FIFOs, a transmit FIFO 134 and a receive FIFO 136, as well as CSRs 138, a scratchpad memory 140 and a hash unit 142. The Fbus 132 transfers data between the ports of the device 31 and the I/O bus interface 28. The ready bus 128 is an 8-bit bus that performs several functions. It is used to read control information about data availability from the device 31, e.g., in the form of ready status flags. It also provides flow control information to the device 31 and may be used to communicate with another network processor 12 that is connected to the Fbus 132. Both buses 128, 132 are accessed by the microengines 22 through the CSRs 138. The

CSRs 138 are used for bus configuration, for accessing the bus interface unit 124, and for inter-thread signaling. They also include a several counters and thread status registers, as will be described. The CSRs 138 are accessed  
5 by the microengines 22 and the core 23. The receive FIFO (RFIFO) 136 includes data buffers for holding data received from the Fbus 132 and is read by the microengines 22. The transmit FIFO (TFIFO) 134 includes data buffers that hold data to be transmitted to the Fbus 132 and is written by  
10 the microengines 22. The scatchpad memory 140 is accessed by the core 23 and microengines 22, and supports a variety of operations, including read and write operations, as well as bit test, bit test/clear and increment operations. The hash unit 142 generates hash indexes for 48-bit or 64-bit  
15 data and is accessed by the microengines 22 during lookup operations.

The processors 23 and 22 issue commands to the push/pull engine interface 122 when accessing one of the resources 120. The push/pull engine interface 122 places  
20 the commands into queues (not shown), arbitrates which commands to service, and moves data between the resources 120, the core 23 and the microengines 22. In addition to servicing requests from the core 23 and microengines 22,



the push/pull engines 122 also service requests from the ready bus 128 to transfer control information to a register in the microengine read transfer registers 80.

When a thread issues a request to a resource 120, a  
5 command is driven onto an internal command bus 150 and placed in queues within the push/pull engine interface 122.

Receive/read-related instructions (such as instructions for reading the CSRS) are written to a "push" command queue.

The CSRs 138 include the following types of  
10 registers: Fbus receive and transmit registers; Fbus and ready bus configuration registers; ready bus control registers; hash unit configuration registers; interrupt registers; and several miscellaneous registers, including a thread status registers. Those of the registers which  
15 pertain to the receive process will be described in further detail.

The interrupt/signal registers include an INTER\_THD\_SIG register for inter-thread signaling. Any thread within the microengines 22 or the core 23 can write  
20 a thread number to this register to signal an inter-thread event.

Further details of the Fbus controller 130 and the ready bus controller 126 are shown in FIG. 5. The ready

bus controller 126 includes a programmable sequencer 160 for retrieving MAC device status information from the MAC device 31 and asserting flow control to the MAC device over the ready bus 128 via ready bus interface logic 161. The

5 Fbus controller 130 includes Fbus interface logic 162, which is used to transfer data to and from the device 31 is controlled by a transmit state machine (TSM) 164 and a receive state machine (RSM) 166. In the embodiment herein, the Fbus 132 may be configured as a bidirectional 64-bit

10 bus, or two dedicated 32-bit buses. In the unidirectional, 32-bit configuration, each of the state machines owns its own 32-bit bus. In the bidirectional configuration, the ownership of the bus is established through arbitration. Accordingly, the Fbus controller 130 further includes a bus

15 arbiter 168 for selecting which state machine owns the Fbus 132.

Some of the relevant CSRs used to program and control the ready bus 128 and Fbus 132 for receive processes are shown in FIGS. 6A-6F. Referring to FIG. 6A,

20 RDYBUS\_TEMPLATE\_PROGx registers 170 are used to store instructions for the ready bus sequencer. Each register of these 32-bit registers 170a, 170b, 170c, includes four, 8-bit instruction fields 172. Referring to FIG. 6E, a

RCV\_RDY\_CTL register 174 specifies the behavior of the receive state machine 166. The format is as follows: a reserved field (bits 31:15) 174a; a fast port mode field (bits 14:13) 174b, which specifies the fast port thread mode, as will be described; an auto push prevent window field (bits 12:10) 174c for specifying the autopush prevent window used by the ready bus sequencer to prevent the receive scheduler from accessing its read transfer registers when an autopush operation (which pushes information to those registers) is about to begin; an autopush enable (bit 9) 174d, used to enable autopush of the receive ready flags; another reserved field (bit 8) 174e; an autopush destination field (bits 7:6) 174f for specifying an autopush operation's destination register; a signal thread enable field (bit 5) 174g which, when set, indicates the thread to be signaled after an autopush operation; and a receive scheduler thread ID (bits 4:0) 174h, which specifies the ID of the microengine thread that has been configured as a receive scheduler.

Referring to FIG. 6C, a REC\_FASTPORT\_CTL register 176 is relevant to receiving packet data from fast ports such as ports 33a and 33b. It enables receive threads to view the current assignment of header and body thread

assignments for these two fast ports, as will be described.

It includes the following fields: a reserved field (bits 31:20) 176a; an FP2\_HDR\_THD\_ID field (bits 19:15) 176b, which specifies the fast port 2 header receive (processing) thread ID; an FP2\_BODY\_THD\_ID field (bits 14:10) 176c for specifying the fast port 2 body receive processing thread ID; an FP1\_HDR\_THD\_ID field (bits 9:5) 176d for specifying the fast port 1 header receive processing thread ID; and an FP1\_BODY\_THD\_ID field (bits 4:0) 176e for specifying the fast port 1 body processing thread ID. The manner in which these fields are used by the RSM 166 will be described in detail later.

Although not depicted in detail, other bus registers include the following: a RDYBUS\_TEMPLATE\_CTL register 178 (FIG. 6D), which maintains the control information for the ready bus and the Fbus controllers, for example, it enables the ready bus sequencer; a RDYBUS\_SYNCH\_COUNT\_DEFAULT register 180 (FIG. 6E), which specifies the program cycle rate of the ready bus sequencer; and an FP\_FASTPORT\_CTL register 182 (FIG. 6F), which specifies how many Fbus clock cycles the RSM 166 must wait between the last data transfer and the next sampling of fast receive status, as will be described.

Referring to FIG. 7, the MAC device 31 provides transmit status flags 200 and receive status flags 202 that indicate whether the amount of data in an associated transmit FIFO 204 or receive FIFO 206 has reached a certain threshold level. The ready bus sequencer 160 periodically polls the ready flags (after selecting either the receive ready flags 202 or the transmit ready flags 200 via a flag select 208) and places them into appropriate ones of the CSRs 138 by transferring the flag data over ready bus data lines 209. In this embodiment, the ready bus includes 8 data lines for transferring flag data from each port to the Fbus interface unit 124. The CSRs in which the flag data are written are defined as RCV\_RDY\_HI/LO registers 210 for receive ready flags and XMIT\_RDY\_HI/LO registers 212 for transmit ready flags, if the ready bus sequencer 160 is programmed to execute receive and transmit ready flag read instructions, respectively.

When the ready bus sequencer is programmed with an appropriate instruction directing it to interrogate MAC receive ready flags, it reads the receive ready flags from the MAC device or devices specified in the instruction and places the flags into a RCV\_RDY\_HI register 210a and a RCV\_RDY\_LO register 210b, collectively, RCV\_RDY registers

210. Each bit in these registers corresponds to a different device port on the I/O bus.

Also, and as shown in the figure, the bus interface unit 124 also supports two fast port receive ready flag pins FAST\_RX1 214a and FAST\_RX2 214b for the two fast ports of the fast MAC device 31. These fast port receive ready flag pins are read by the RSM 166 directly and placed into an RCV\_RDY\_CNT register 216. The RCV\_RDY\_CNT register 216 is one of several used by the receive scheduler thread to determine how to issue a receive request. It also indicates whether a flow control request is issued.

Referring to FIG. 8A, the format of the RCV\_RDY\_CNT register 216 is as follows: bits 31:28 are defined as a reserved field 216a; bit 27 is defined as a ready bus master field 216b and is used to indicate whether the ready bus 128 is configured as a master or slave; a field corresponding to bit 26 216c provides flow control information; bits 25 and 24 correspond to FRDY2 field 216d and FRDY1 field 216e, respectively. The FRDY2 216d and FRDY1 216e are used to store the values of the FAST\_RX2 pin 214b and FAST\_RX1 pin 214a, respectively, both of which are sampled by the RSM 166 each Fbus clock cycle; bits 23:16 correspond to a reserved field 216f; a receive request

count field (bits 15:8) 216g specifies a receive request count, which is incremented after the RSM 166 completes a receive request and data is available in the RFIFO 136; a receive ready count field (bits 7:0) 216h specifies a  
5 receive ready count, an 8-bit counter that is incremented each time the ready bus sequencer 160 writes the ready bus registers RCV\_RDY\_CNT register 216, the RCV\_RDY\_LO register 210b and RCV\_RDY\_HI register 210a to the receive scheduler read transfer registers.

10           There are two techniques for reading the ready bus registers: "autopush" and polling. The autopush instruction may be executed by the ready bus sequencer 160 during a receive process (rxautopush) or a transmit process (txautopush). Polling requires that a microengine thread  
15 periodically issue read references to the I/O bus interface 28.

          The rxautopush operation performs several functions. It increments the receive ready count in the RCV\_RDY\_CNT register 216. If enabled by the RCV\_RDY\_CTL register 174,  
20 it automatically writes the RCV\_RDY\_CNT 216, the RCV\_RDY\_LO and RCV\_RDY\_HI registers 210b, 210a to the receive scheduler read transfer registers 80 (FIG. 2) and signals to the receive scheduler thread 92 (via a context event

signal) when the rxautopush operation is complete.

The ready bus sequencer 160 polls the MAC FIFO receive ready flags periodically and asynchronously to other events occurring in the processor 12. Ideally, the rate at which the MAC FIFO receive ready flags are polled is greater than the maximum rate at which the data is arriving at the MAC device ports. Thus, it is necessary for the receive scheduler thread 92 to determine whether the MAC FIFO receive ready flags read by the ready bus sequencer 160 are new, or whether they have been read already. The rxautopush instruction increments the receive ready count in the RCV\_RDY\_CNT register 216 each time the instruction executes. The RCV\_RDY\_CNT register 216 can be used by the receive scheduler thread 92 to determine whether the state of specific flags have to be evaluated or whether they can be ignored because receive requests have been issued and the port is currently being serviced. For example, if the FIFO threshold for a Gigabit Ethernet port is set so that the receive ready flags are asserted when 64 bytes of data are in the MAC receive FIFO 206, then the state of the flags does not change until the next 64 bytes arrive 5120 ns later. If the sequencer 160 is programmed to collect the flags four times each 5120 ns period, the



next three sets of ready flags that are collected by the ready bus sequencer 160 can be ignored.

When the receive ready count is used to monitor the freshness of the receive ready flags, there is a possibility that the receive ready flags will be ignored when they are providing new status. For a more accurate determination of ready flag freshness, the receive request count may be used. Each time a receive request is completed and the receive control information is pushed onto the RCV\_CNTL register 232, the the RSM 166 increments the receive request count. The count is recorded in the RCV\_RDY\_CNT register the first time the ready bus sequencer executes an rxrdy instruction for each program loop. The receive scheduler thread 92 can use this count to track how many requests the receive state machine has completed. As the receive scheduler thread issues commands, it can maintain a list of the receive requests it submits and the ports associated with each such request.

Referring to FIGS. 8B and 8C, the registers RCV\_RDY\_HI 210a and RCV\_RDY\_LO 210b have a flag bit 217a, 217b, respectively, corresponding to each port.

Referring to FIG. 9, the receive scheduler thread 92 performs its tasks at a rate that ensures that the RSM 166

is always busy, that is, that there is always a receive request waiting to be processed by the RSM 166. Several tasks performed by the receive scheduler 92 are as follows.

The receive scheduler 92 determines which ports need to be serviced by reading the RCV\_RDY\_HI, RCV\_RDY\_LO and RCV\_RDY\_CNT registers 210a, 210b and 216, respectively. The receive scheduler 92 also determines which receive ready flags are new and which are old using either the receive request count or the receive ready count in the RCV\_RDY\_CNT register, as described above. It tracks the thread processing status of the other microengine threads by reading thread done status CSRs 240. The receive scheduler thread 92 initiates transfers across the Fbus 132 via the ready bus, while the receive state machine 166 performs the actual read transfer on the Fbus 132. The receive scheduler 92 interfaces to the receive state machine 166 through two FBI CSRs 138: an RCV\_REQ register 230 and an RCV\_CNTL register 232. The RCV\_REQ register 230 instructs the receive state machine on how to receive data from the Fbus 132.

Still referring to FIG. 9, a process of initiating an Fbus receive transfer is shown. Having received ready status information from the RCV\_RDY\_HI/LO registers 210a,

210b as well as thread availability from the thread done register 240 (transaction 1, as indicated by the arrow labeled "1"), the receive scheduler thread 92 determines if there is room in the RCV\_REQ FIFO 230 for another receive request. If it determines that RCV\_REQ FIFO 230 has room to receive a request, the receive scheduler thread 92 writes a receive request by pushing data into the RCV\_REQ FIFO 230 (transaction 2). The RSM 166 processes the request in the RCV\_REQ FIFO 230 (transaction 3). The RSM 166 responds to the request by moving the requested data into the RFIFO 136 (transaction 4), writing associated control information to the RCV\_CTL FIFO 232 (transaction 5) and generating a start\_receive signal event to the receive processing thread 96 specified in the receive request (transaction 6). The RFIFO 136 includes 16 elements 241, each element for storing a 64 byte unit or segment of data referred to herein as a MAC packet ("MPKT"). The RSM 166 reads packets from the MAC ports in fragments equal in size to one or two RFIFO elements, that is, MPKTs. The specified receive processing thread 96 responds to the signal event by reading the control information from the RCV\_CTL register 232 (transaction 7). It uses the control information to determine, among other pieces of

information, where the data is located in the RFIFO 136. The receive processing thread 96 reads the data from the RFIFO 136 on quadword boundaries into its read transfer registers or moves the data directly into the SDRAM  
5 (transaction 8).

The RCV\_REQ register 230 is used to initiate a receive transfer on the Fbus and is mapped to a two-entry FIFO that is written by the microengines. The I/O bus interface 28 provides signals (not shown) to the receive  
10 scheduler thread indicating that the RCV\_REQ FIFO 236 has room available for another receive request and that the last issued request has been stored in the RCV\_REQ register 230.

Referring to FIG. 10A, the RCV\_REQ FIFO 230 includes  
15 two entries 231. The format of each entry 231 is as follows. The first two bits correspond to a reserved field 230a. Bit 29 is an FA field 230b for specifying the maximum number of Fbus accesses to be performed for this request. A THSG field (bits 28:27) 230c is a two-bit  
20 thread message field that allows the scheduler thread to pass a message to the assigned receive thread through the ready state machine, which copies this message to the RCV\_CNTL register. An SL field 230d (bit 26) is used in

cases where status information is transferred following the EOP MPKT. It indicates whether two or one 32-bit bus accesses are required in a 32-bit Fbus configuration. An E1 field 230e (bits 21:18) and an E2 field (bits 25:22) 230f specify the RFIFO element to receive the transferred data. If only 1 MPKT is received, it is placed in the element indicated by the E1 field. If two MPKTs are received, then the second MPKT is placed in the RFIFO element indicated by the E2 field. An FS field (bits 10 17:16) 230g specifies use of a fast or slow port mode, that is, whether the request is directed to a fast or slow port. The fast port mode setting signifies to the RSM that a sequence number is to be associated with the request and that it will be handling speculative requests, which will 15 be discussed in further detail later. An NFE field (bit 15) 230h specifies the number of RFIFO elements to be filled (i.e., one or two elements). The IGFR field (bit 13) 230i is used only if fast port mode is selected and indicates to the RSM that it should process the request 20 regardless of the status of the fast ready flag pins. An SIGRS field (bit 11) 230j, if set, indicates that the receive scheduler be signaled upon completion of the receive request. A TID field (bits 10:6) 230k specifies

the receive thread to be notified or signaled after the receive request is processed. Therefore, if bit 11 is set, the RCV\_REQ entry must be read twice, once by the receive thread and once by the receive scheduler thread, before it  
5 can be removed from the RCV\_REQ FIFO. An RM field (bits 5:3) 230l specified the ID of the MAC device that has been selected by the receive scheduler. Lastly, an RP field (bits 2:0) 230m specifies which port of the MAC device specified in the RM field 230l has been selected.

10           The RSM 166 reads the RCV\_REQ register entry 231 to determine how it should receive data from the Fbus 132, that is, how the signaling should be performed on the Fbus, where the data should be placed in the RFIFO and which microengine thread should be signaled once the data is  
15 received. The RSM 166 looks for a valid receive request in the RCV\_REQ FIFO 230. It selects the MAC device identified in the RM field and selects the specified port within the MAC by asserting the appropriate control signals. It then begins receiving data from the MAC device on the Fbus data  
20 lines. The receive state machine always attempts to read either eight or nine quadwords of data from the MAC device on the Fbus as specified in the receive request. If the  
MAC device asserts the EOP signal, the RSM 166 terminates

the receive early (before eight or nine accesses are made).  
The RSM 166 calculates the total bytes received for each  
receive request and reports the value in the RCV\_CNTL  
register 232. If EOP is received, the RSM 166 determines  
5 the number of valid bytes in the last received data cycle.

The RCV\_CNTL register 232 is mapped to a four-entry  
FIFO (referred to herein as RCV\_CNTL\_FIFO 232) that is  
written by the receive state machine and read by the  
microengine thread. The I/O bus interface 28 signals the  
10 assigned thread when a valid entry reaches the top of the  
RCV\_CNTL FIFO. When a microengine thread reads the  
RCV\_CNTL register, the data is popped off the FIFO. If the  
SIGRS field 230i is set in the RCV\_REQ register 230, the  
receive scheduler thread 92 specified in the RCV\_CNTL  
15 register 232 is signaled in addition to the thread  
specified in TID field 230k. In this case, the data in the  
RCV\_CNTL register 232 is read twice before the receive  
request data is retired from the RCV\_CNTL FIFO 232 and the  
next thread is signaled. The receive state machine writes  
20 to the RCV\_CNTL register 232 as long as the FIFO is not  
full. If the RCV\_CNTL FIFO 232 is full, the receive state  
machine stalls and stops accepting any more receive  
requests.

Referring to FIG. 10B, the RCV\_CNTL FIFO 232 provides instruction to the signaled thread (i.e., the thread specified in TID) to process the data. As indicated above, the RCV\_CNTL FIFO includes 4 entries 233. The

5 format of the RCV\_CNTL FIFO entry 233 is as follows: a THMSG field (31:30) 23a includes the 2-bit message copied by the RSM from RCV\_REQ register[28:27]. A MACPORT/THD field (bits 29:24) 232b specifies either the MAC port number or a receive thread ID, as will be described in

10 further detail below. An SOP\_SEQ field (23:20) 232c is used for fast ports and indicates a packet sequence number as an SOP (start-of-packet) sequence number if the SOP was asserted during the receive data transfer and indicates an MPKT sequence number if SOP was not so asserted. An RF

15 field 232d and RERR field 232e (bits 19 and 18, respectively) both convey receive error information. An SE field 232f (17:14) and an FE field 232g (13:10) are copies of the E2 and E1 fields, respectively, of the RCV\_REQ. An EF field (bit 9) 232h specifies the number of RFIFO

20 elements which were filled by the receive request. An SN field (bit 8) 232i is used for fast ports and indicates whether the sequence number specified in SOP\_SEQ field 232c is associated with fast port 1 or fast port 2. A VLD BYTES



field (7:2) 232j specifies the number of valid bytes in the RFIFO element if the element contains in EOP MPKT. An EOP field (bit 1) 232k indicates that the MPKT is an EOP MPKT.

An SOP field (bit 0) 232l indicates that the MPKT is an  
5 SOP MPKT.

The thread done registers 240 can be read and written to by the threads using a CSR instruction. Using these registers, the receive scheduler thread can determine which RFIFO elements are not in use. The THREAD\_DONE CSRs  
10 240 support a two-bit message for each microengine thread.

The assigned receive thread may write a two-bit message to this register to indicate that it has completed its task. Each time a message is written to the THREAD\_DONE register, the current message is logically ORed with the new message.

15 The bit values in the THREAD\_DONE registers are cleared by writing a "1", so the scheduler may clear the messages by writing the data read back to the THREAD\_DONE register. The definition of the 2-bit status field is determined in software.

20 The assigned receive processing threads write their status to the THREAD\_DONE register whenever the status changes. When the receive scheduler reads the THREAD\_DONE register, it can look at the returned value to determine

the status of each thread and then update its thread/port assignment list.

The packet rate of a fast port (e.g., a Gigabit port) is such that the rate at which the receive state machine reads MPKTs from a single port is so fast that a receive thread may not be able to process an MPKT before the receive state machine brings in another MPKT from the same port. That is, a fast port may require the use of a number of RFIFO elements and receive threads in parallel to maintain full line rate. The amount of processing required for an MPKT may include header processing (e.g., header modification, forward lookup) or simply moving a packet body fragment to memory.

Fast packets and, in some cases, fast MPKTs (i.e., MPKTs which make up packets received from fast ports) can be processed in parallel and by different threads, so there is a need to maintain intra-packet order and inter-packet order for a given port. Thus, to maintain packet order for packets received from fast ports, the network processor uses sequence numbers, one set for each high-speed port. Each set of sequence numbers provides a network packet sequence number, an MPKT sequence number and an enqueue sequence number. These sequence numbers are maintained as

4-bit counters within the I/O bus interface 28 and automatically roll over to zero once they reach a count of fifteen.

The sequence numbers are maintained in Fbus receive registers (CSRs). Referring to FIG. 11A, sequence numbers registers 270 include an SOP\_SEQ1 register 272 having an SOP\_SEQ1 field 273 and an SOP\_SEQ2 register 274, which has an SOP\_SEQ2 field 275. These fields store SOP sequence numbers for their respective fast ports and are incremented by the RSM. Referring to FIG. 11B, enqueue sequence number registers 276 include an ENQUEUE\_SEQ1 register 278 having an ENQUEUE\_SEQ1 field 279 for storing an enqueue sequence number for fast port 1 and an ENQUEUE\_SEQ2 register 280, which includes an ENQUEUE\_SEQ2 field 281 for storing enqueue SOP sequence number for fast port 2. The enqueue sequence numbers are incremented by the receive processing threads.

The network packet sequence number in either the SOP\_SEQ1 register (for fast port 1) or SOP\_SEQ2 register (for fast port 2) register is placed into the RCV\_CNTL register, and incremented at the same time. The receive state machine increments the packet sequence numbers in a manner that allows the receive processing threads to track

not only the sequence of the network packets, but also the sequence of the individual MPKTs. If the SOP signal is detected during a receive request, the network packet sequence number provides a sequence number based on a network packet (hereinafter referred to as an SOP sequence number). If the SOP signal is not detected during a receive request, the packet sequence number is based on an MPKT (hereinafter, MPKT sequence number). The receive threads can determine the type of packet sequence number since the RCV\_CNTL register contains both the packet sequence number and SOP status.

The SOP and MPKT sequence numbers for each fast port are implemented as 4-bit counters. The SOP sequence number counter is incremented each time an SOP is detected. An MPKT sequence number counter receives the SOP sequence number whenever the SOP signal is asserted, and is incremented once per receive request when the SOP signal is not detected.

The enqueue sequence numbers are used by the receive processing threads to determine whether it is their turn to place a complete network packet onto a transmit queue. When an entire network packet has been received, the receive processing thread reads the enqueue sequence number

from the appropriate enqueue\_seq register. If the enqueue sequence number matches the SOP sequence number assigned to the packet, the receive processing thread can place the packet onto a transmit queue. If the enqueue sequence number does not match, the receive processing thread waits for a "sequence number change" signal event to occur. When the event occurs, the receive processing thread reads the enqueue sequence number again and checks for a match. If a match occurs, the packet may be placed onto a transmit queue.

After a packet is placed on a transmit queue, the receive processing thread increments the enqueue sequence number. The enqueue sequence numbers are incremented by writing to either the ENQUEUE\_SEQ1 or ENQUEUE\_SEQ2 register. A receive processing thread may choose to write its processing status to the THREAD\_DONE register as well as increment the enqueue sequence number at the same time.

This can be accomplished with a single write instruction to additional CSRs, a THREAD\_DONE\_INCR1 register or the THREAD\_DONE\_INCR2 register (not shown).

The receive scheduler thread controls the rate at which it issues receive requests. It issues a number of receive requests that is no more than that required by a

port, but is sufficient to prevent an overflow of that port's receive FIFO.

When using slower ports, such as 10/100 BaseT Ethernet ports, the receive scheduler thread reads the MAC  
5 receive FIFO ready flags for multiple ports, determines which ports have data available, and issues receive requests based on the knowledge that data is available in the MAC receive FIFO. Since it reads multiple receive FIFO ready flags each time, it can issue multiple receive  
10 requests before it has to read the flags again.

Because fast ports operate at a much higher data rate than slow ports and the latencies associated with certain tasks, e.g., reading the receive ready flags from a port or from the RCV\_RDY\_HI/LO registers, writing a receive request to  
15 RCV\_REQ, may be greater than that packet arrival rate, the rate at which a single MAC port must be serviced cannot be sustained by issuing receive requests only when data is known to be available in a device port receive FIFO.

Therefore, the receive scheduler thread uses  
20 speculative requests for high-speed ports. That is, the receive scheduler thread issues multiple receive requests to a port based on the speculation that there is data available in that port's receive FIFO. At the time the RSM

166 processes each receive request, it determines if data is actually available at the port. Based on this determination, the RSM 166 either processes or cancels the request.

5           The RSM 166 determines whether there is data available at either of the two fast ports by reading the fast receive ready pins (FAST\_RX1 214a and FAST\_RX2 214b of FIG. 7). These pins 214a, 214b provide a direct connection to their respective MAC port's receive FIFO ready flag. The  
10   MAC ports assert these signals when the receive FIFO fullness threshold level is reached or an entire packet has been received.

          If a fast ready pin is not asserted, the RSM 166 cancels the pending request and writes a cancel message  
15   into the RCV\_CNTL register's message field. It then signals the assigned receive processing thread. The receive processing thread is programmed to read the RCV\_CNTL register, interpret the cancel message correctly and indicate to the receive scheduler thread that it is  
20   available for other tasks.

          The state of the two fast ready pins is indicated in the FRDY2 field 216d (for port 2) and FRDY1 field 216e (for port 1) of the RCV\_RDY\_CNT register 216 (shown in FIG. 8A).

The receive scheduler thread reads the fast ready flags from the RCV\_RDY\_CNT register 216 fields 216d, 216e on a periodic basis to determine when it should issue receive requests. It issues enough receive requests to cover the  
5 data that might have arrived in the MAC port 33 since the last time it read the fast ready flags.

The receive state machine 166 supports three fast port modes that determine how receive processing threads are assigned to process packet data in the RFIFO. These  
10 fast port modes are referred to as single thread, header/body thread and explicit thread modes. When selecting a mode, the network processor considers the following: availability of threads to process each receive request; execution time for the receive thread. The modes  
15 need to understand where one network packet ends and the next one begins. To that end, they rely on the beginning of the network packet as corresponding to the assertion of SOP and the ending of the network packet corresponding to the assertion of EOP. Referring back to FIG. 6B, the fast  
20 port mode field 174b of RCV\_RDY\_CTL register 176 defines the three modes as single thread '00', header/body '01' and explicit '10'.

The single thread mode assigns a single thread to



each packet when using speculative requests. If the single thread mode is specified in the RCV\_RDY\_CTL register 176 and fast port thread mode (RCV\_REQ[17:16]) is set, the RSM 166 performs in the following manner. If the RSM 166  
5 detects an SOP in the receive data transfer for the MPKT, it signals the thread specified in the RCV\_REQ register 230. That is, it writes the thread ID of the specified thread to the TID field 230k. It also saves that thread ID in the appropriate header field of the REC\_FASTPORT\_CTL  
10 register 176. If SOP is not detected, the RSM 166 ignores the thread ID specified in the RCV\_REQ register and signals the thread specified in the header field in the REC\_FASTPORT\_CTL register. The RSM 166 writes the unused thread ID to the RCV\_CNTL register MACPORT/THD field 232b.  
15 The unused ID is returned to the receive scheduler thread so the receive scheduler thread can update its thread availability list. To return the thread ID, the RSM 166 signals the receive thread when the receive request is complete and the receive thread passes the unused thread ID  
20 to the receive scheduler using inter-thread communications. Alternatively, the receive scheduler thread can request that it be signaled as well as the receive processing thread after the RSM completes the receive request. In

this case, RCV\_CNTL must be read twice before data is removed from the RCV\_CNTL FIFO. In most cases, the receive processing thread reads it once and the receive scheduler thread also reads it once. If two reads are not performed, the RSM stalls. In another alternative, the RSM signals the receive processing thread when the receive request is complete and the receive processing thread returns the unused thread to the receive scheduler thread using an inter-thread signaling register which, like the thread done registers, has a bit for each thread and is read periodically by the receive scheduler to determine thread availability. It sets the bit corresponding to the unused thread ID in that register, which is then read by the receive scheduler thread.

15 In the header/body mode, two threads are assigned to process the MPKTs within a network packet. The first thread serves as the header thread and is responsible for processing the header to determine how to forward the packet. The second thread is the body thread, which is responsible for moving the remainder of the packet to the SDRAM. When the body thread completes its task, it uses inter-thread signaling to notify the header thread where the body of the packet is located. The header thread can

then place the packet onto a transmit queue.

The RSM 166 supports the header and body threads in the following manner. If the RSM 166 detects an SOP, it signals the thread specified in RCV\_REQ register and saves  
5 the thread number in the header field of REC\_FASTPORT\_CTL register 176. When it processes the next request, it signals the thread specified in RCV\_REQ register 230 and saves the thread number in the body field of REC\_FAST\_PORT\_CTL register 176. From this point forward,  
10 the RSM ignores the thread ID presented in the RCV\_REQ register 230 and signals the body thread specified in REC\_FASTPORT\_CTL register 176. The RSM writes the unused thread ID to the RCV\_CNTL register's MACPORT/THD field 232b.  
As with the single thread mode, the unused thread ID is  
15 returned to the receive scheduler thread so the receive scheduler thread knows that the thread is available for processing.

In explicit thread mode, the RSM always uses the thread assignment in the receive request as indicated by  
20 the RCV\_REQ register 230. In this mode, the receive scheduler thread provides each receive processing thread with the ID of the thread assigned to the next MPKT receive request so that the thread can signal the next assigned

thread for the next consecutive MPKT that is it done, the exception being the last thread in line, which receives instead the thread ID of the header thread. Additionally, each thread provides the next assigned thread with a  
5 pointer to the buffer memory, thus ensuring the MPKTs for a given network packet are queued in packet memory in the order in which they arrived. Once the thread assigned to the EOP MPKT has completed processing and has been signaled by the thread for the previous MPKT, it notifies the header  
10 thread that the entire packet can be enqueued on the transmit queue, provided, that is, that the enqueue sequence number matches the SOP sequence number of the MPKT processed by the header thread. The MPKT sequence number is provided to ensure that MPKTS are queued in the correct  
15 order.

Referring to FIG. 12, an overview of the fast port receive processing for a selected fast port 300 is shown. The receive scheduler thread selects or assigns 302 an available thread to the port and issues 304 a receive  
20 request specifying the assigned thread. As noted in dashed lines, in explicit mode, the scheduler selects 306 a secondary thread as a thread to be assigned in the next receive request and stores the secondary thread in a memory.

location designated as corresponding to the RFIFO element to which it will be written. The RSM checks 308 the fast ready flag for the fast port. The RSM determines 310 if it is asserted. If it is asserted, the RSM processes 312 the  
5 receive request, and responds to the request by transferring 314 the requested MPKT into an RFIFO element indicated by the request, and performs the step of posting 316 a RVC\_CNTL FIFO entry (according to the fast port mode specified in the RCV\_RDY\_CTL register 174) to the RCV\_CNTL  
10 FIFO and, at the same time, signaling the assigned thread (and any other threads, e.g., the scheduler, as specified by the request). Once these steps are completed, the assigned receive processing thread processes 318 the MPKT as instructed by the control information in the RCV\_CNTL  
15 register and the fast port mode. If the ready flag is not asserted, it determines 319 if the IGFR field is set in the RCV\_REQ entry. If not set, the RSM cancels 320 the request and returns the ID of the thread. If it is set, the RSM proceeds to process the request.

20 Referring to FIG. 13A, the RCV\_CNTL entry posting and thread signaling of 316 (FIG. 12) includes, for the single thread mode, the following. The RSM determines 330 if SOP is asserted during the receive data cycle. If so,

it places 332 the SOP sequence number in the SOP\_SEQ field, increments 334 the SOP\_SEQx counter, sets 336 the SOP bit, writes 338 the specified thread ID to the TID field as well as saves 340 it in the REC\_FASTPORT\_CTL register header field for the appropriate fast port. It signals 342 the specified thread. If SOP is not asserted, the RSM writes 346 the MPKT sequence number to the sequence number field, and increments 348 that number. It sets 350 the TID field to the ID of the thread indicated in the header field of the REC\_FASTPORT\_CTL register (i.e., the TID for the last MPKT that was an SOP MPKT). It also writes 352 the unused receive processing thread, that is, the thread specified by the receive request to the MACPORT/THD field. It signals 354 both the assigned thread and the scheduler to read the register, the assigned thread so that it knows how to process the packet and the receive scheduler thread so that it knows the specified thread was not used and is therefore available for a new assignment.

Referring to FIG. 13B, the processing of the MPKT (318, FIG. 12) for the single thread mode is as follows.

If the assigned processing thread determines 360 that the MPKT is as SOP MPKT (as indicated by the RCV\_CNTL

register), the assigned processing thread parses 362 the

header and performs a lookup 364 (based in the header and hash information retrieved from the hash table). It moves 366 both the header as processed, along with forwarding information stored in the SDRAM forwarding tables and the remainder of the MPKT (i.e., payload) into a temporary queue in packet buffer memory. If it determines 368 that the MPKT is an EOP, then the assigned thread assumes 370 that the packet is ready to be enqueued in the transmit queue for the forwarding port indicated by the forwarding information. The enqueueing process will be described with reference to FIG. 18. If the MPKT is not an SOP, the processing thread moves 372 the payload data to buffer memory (in SDRAM) and then determines 374 if it is an EOP. If it is an EOP, the processing thread is ready to enqueue the packet 376. If the MPKT is not an EOP, then the processing thread signals 378 that it is done (via inter-signaling methods, e.g., write thread done register).

Referring to FIG. 14A, the RCV\_CNTL entry posting and signaling of threads 316 includes, for the dual (or header/body) thread mode, the following. The RSM determines 380 if SOP is asserted during the receive data cycle. If so, it places 382 the SOP sequence number in the SOP\_SEQx field, increments 384 the SOP\_SEQx counter, writes

386 the specified thread ID to the TID field as well as  
saves 388 it in the REC\_FASTPORT\_CTL register header field  
for the appropriate fast port. It signals 390 the  
specified thread. If SOP is not asserted, the RSM writes  
5 392 the MPKT sequence number to the sequence number field,  
and increments 394 that number. It determines 396 if the  
last request was for an SOP MPKT. If so, it signals 398  
the specified thread, sets 400 the ID of that thread in the  
TID field as well as the appropriate body field of the  
10 REC\_FASTPORT\_CTL register. It also indicates 402 in the  
MACPORT/THD field the ID of the header thread (so that the  
header thread may be signaled when the entire packet has  
been received and processed). If the last request was not  
an SOP MPKT, the RSM signals 404 the thread specified in  
15 the body, writes 406 that ID to TID field and specifies 408  
the ID of the unused thread of the receive request in the  
MACPORT/THD field (to return to the pool of available  
receive processing threads). It also signals 410 the  
scheduler so that the scheduler, in addition to the  
20 signaled receive processing thread, may read the rec\_cntl  
register entry before it is removed from the RCV\_CNTL FIFO.

Referring to FIG. 14B, the MPKT is processed by the  
"assigned" thread in the dual thread mode as follows. If



the thread determines 412 that the MPKT is an SOP MPKT, it processes 414 the header and payload data in the same manner as described above (i.e., parses the header, etc.).

If it determines 416 that the MPKT being processing is an  
5 EOP, that is, the MPKT is a minimum sized network packet, then it assumes 418 the MPKT is ready for enqueueing. If the MPKT is not the last MPKT in a packet, then the thread (which is the header thread) awaits notification 420 of EOP. Once it receives such notification 422, the packet is  
10 ready to be enqueued in the transmit queue. If the MPKT is not an SOP but the continuation of a packet, the thread stores 424 the payload in the temporary queue in SDRAM at a buffer location designated by the header thread. If it determines 426 that the MPKT is an EOP, then it signals 428  
15 to the scheduler and the header thread (as identified in the MACPORT/THD field) that it is done. It thus determines 430 that the complete packet is now ready to be enqueued. If the MPKT is not an EOP, it simply signals 432 to the scheduler that it is done processing its MPKT and is  
20 available for work.

Referring to FIG. 15A, the posting of the RCV\_CNTL entry and signaling of threads includes, for the explicit mode, the following steps. As in the other fast

port modes, the RSM determines 440 if SOP is asserted during the receive data cycle. If so, it places 442 the SOP sequence number in the SOP\_SEQx field, increments 444 the SOP\_SEQx counter, writes 446 the specified thread ID to the TID field. It signals 448 the specified thread. If SOP is not asserted, the RSM writes 450 the MPKT sequence number to the sequence number field, increments 452 that number and signals 454 the specified thread.

Referring to FIG. 15B, the receive thread processing the fast port MPKT according to the explicit mode as follows. If the specified thread determines 460 that the MPKT is an SOP MPKT, the specified thread processes 462 the header, moves the payload and processed header to buffer memory 464. If it determines 465 that an EOP bit is set in the RCV\_CNTL register entry, then it concludes 466 that the MPKT is ready to be enqueued in the appropriate port transmit queue. If the EOP is not set, that is, the MPKT is not an EOP MPKT, the thread (in this case, the header thread) passes 468 a pointer to the next available buffer location to the secondary thread ID that was specified by the scheduler in a common location corresponding to the RFIFO element in which the MPKT was stored. It then awaits

notification 470 from the EOP thread. If the MPKT is not an SOP MPKT, it receives 472 a pointer to a buffer location in SDRAM and queues 474 the MPKT in the buffer memory at the location pointed to by the pointer. If the thread  
5 determines 475 that the MPKT is an EOP MPKT, the thread signals 476 that it is done and that the MPKT is an EOP so that the header thread know that the network packet to which this EOP MPKT belongs is ready to be enqueued in the transmit queue. If the MPKT is not an EOP, the processing  
10 thread increments 478 the pointer to the next available buffer location and passes 480 the pointer to the thread processing the next, consecutive MPKT, that is, the ID specified by the scheduler as the secondary thread in a memory location corresponding to the RFIFO element in which  
15 the MPKT was stored.

Referring to FIG. 16, the process of enqueueing is illustrated. The header thread (which has identified an EOP or received notification of an EOP from another thread, as previously described), first determines if it is this  
20 particular packet's turn to be enqueued. It determines 490 if the enqueue sequence # is equal to the SOP sequence number that was associated with the SOP MPKT. If they are  
equal, the header thread links 494 the network packet (now equal to the

stored in its entirety in the packet buffer memory in  
SDRAM) to the port transmit queue (located in SRAM). It  
increments 496 the enqueue sequence number and notifies 498  
the scheduler of completion. If the SOP sequence number is  
5 not equal to the enqueue sequence number, it waits to  
receive a signal indicating that the SOP sequence number  
has changed 500 and again compares the two sequence  
numbers.

It will be appreciated that the processes depicted  
10 in FIGS. 12-16 assume that no packet exemptions occurred,  
that the thread are able to handle the packet processing  
without assistance from the core processor. Such  
assistance, if invoked, in no way changes the manner in  
which packet order is maintained. Further, the processes  
15 of FIGS. 12-16 assume the availability of FIFO, e.g.,  
RFIFO, space. Although not described in the steps of FIGS.  
12-16 above, it will be appreciated that the various state  
machines must determine if there is room available in a  
FIFO prior to writing new entries to that FIFO. If a  
20 particular FIFO is full, the state machine will wait until  
the appropriate number of entries has been retired from  
that FIFO.

Additions, subtractions, and other modifications of

the preferred embodiments of the invention will be apparent to those practiced in this field and are within the scope of the following claims.

What is claimed is:

1. A method of forwarding data, comprising:  
5 associating control information with data received from a first port; and  
using the associated control information to enqueue the data for transmission to a second port in the same order in which the data was received from the first port.  
10
2. The method of claim 1, wherein the control information includes sequence numbers.
3. The method of claim 2, wherein the data comprises  
15 units of data and the units of data are associated with a network packet.
4. The method of claim 3, wherein associating  
associates first sequence numbers with the units of data as  
20 they are received from the first port.
5. The method of claim 1, further comprising:  
processing the units of data by receive processing

program threads to determine the second port to which the units of data are to be transmitted.

6. The method of claim 4, wherein associating further  
5 comprises maintaining second sequence numbers, and wherein using comprises:

determining if the first sequence numbers are equal to the second sequence numbers to order the units of data after the units of data are processed.

10

7. The method of claim 2, further comprising:  
controlling transfer of the data from the first port to the receive processing program threads for processing.

15 8. The method of claim 7, wherein controlling comprises:

assigning the receive processing program threads to process the data.

20 9. The method of claim 8, wherein controlling comprises:

directing the units of data to the attention of the respective assigned receive processing program threads.

10. The method of claim 8, wherein controlling comprises:

directing the units of data to the attention of a  
5 single one of the respective assigned receive processing  
program threads.

11. The method of claim 8, wherein controlling comprises:

10 directing the units of data for processing by a  
first and a second different receive processing program  
thread, the first processing program thread handling a  
first one of the data units that comprises a packet header  
and a portion of payload data, and the second receive  
15 processing program thread handling a second one of the data  
units that comprises another portion of the payload data.

12. The method of claim 3, further comprising:

maintaining a sequence number count for generating  
20 start-of-packet sequence numbers; and

incrementing the sequence number count upon  
associating a current count value of the sequence number  
count with a data unit as an start-of-packet sequence



number when the data unit is recognized as corresponding to a start of a new packet.

13. The method of claim 3, further comprising:

5 maintaining an enqueue sequence number count for generating enqueue sequence numbers; and

incrementing the enqueue sequence number count after determining that a packet is ready to be enqueued for transmission to the second port.

10

14. A processor for forwarding data from a first port to a second port comprises:

a microengine for executing program threads, the threads including a receive scheduler program thread for  
15 issuing requests for transfer of units of data from the first port and receive processing program threads;

a bus interface, responsive to the microengine, for receiving the units of data from the first port and directing the units of data to the receive processing  
20 program threads for processing and enqueueing the units of data in the order in which they were received from the first port for transmission to the second port.

15. The processor of claim 14, wherein the bus interface uses sequence numbers to ensure that the units of data are enqueued in the order in which they were received from the first.

5

16. The processor of claim 15, wherein the bus interface associates a first set of the sequence numbers with the units of data as they are received from the first port and maintains a second set of sequence numbers for use by the  
10 receive processing program threads in determining the order in which the units of data are to be enqueued.

17. The processor of claim 14, wherein the bus interface indicates to the receive scheduler program thread whether  
15 the first port has data available for processing by one or more of the receive processing program threads.

18. The processor of claim 14, wherein the receive scheduler program thread assigns available threads from  
20 among the one or more receive processing program threads to process the units of data.

19. The processor of claim 14, wherein the bus interface

comprises a receive state machine for controlling the transfer of the data units from the first port.

20. The processor of claim 19, wherein the units of data  
5 are associated with a network packet.

21. The processor of claim 20, wherein the receive scheduler program thread assigns each of the units of data to different ones of the receive processing program  
10 threads.

22. The processor of claim 21, wherein the receive state machine directs the units of data to the attention of the respective assigned different ones of the receive  
15 processing program threads.

23. The processor of claim 21, wherein the receive state machine directs the units of data to the attention of a single one of the respective assigned different ones of the  
20 receive processing program threads.

24. The processor of claim 21, wherein the receive state machine directs the units of data for processing by a first

and a second different receive processing program thread,  
the first processing program thread handling a first one of  
the data units that comprises a packet header and a portion  
of payload data; and the second receive processing program  
5 thread handling a second one of the data units that  
comprises another portion of the payload data.

25. An article comprising a computer-readable medium  
which stores computer-executable instructions for  
10 forwarding data, the instructions causing a computer to:  
associate control information with data received  
from a first port; and  
use the associated control information to enqueue  
the data for transmission to a second port in the same  
15 order in which the data was received from the first port.

26. The article of claim 25, wherein the control  
information includes sequence numbers.

20 27. The article of claim 26, wherein the instructions to  
use the associated control information comprise  
instructions causing a computer to:

determine the order in which the data are to be  
enqueued from the sequence numbers.

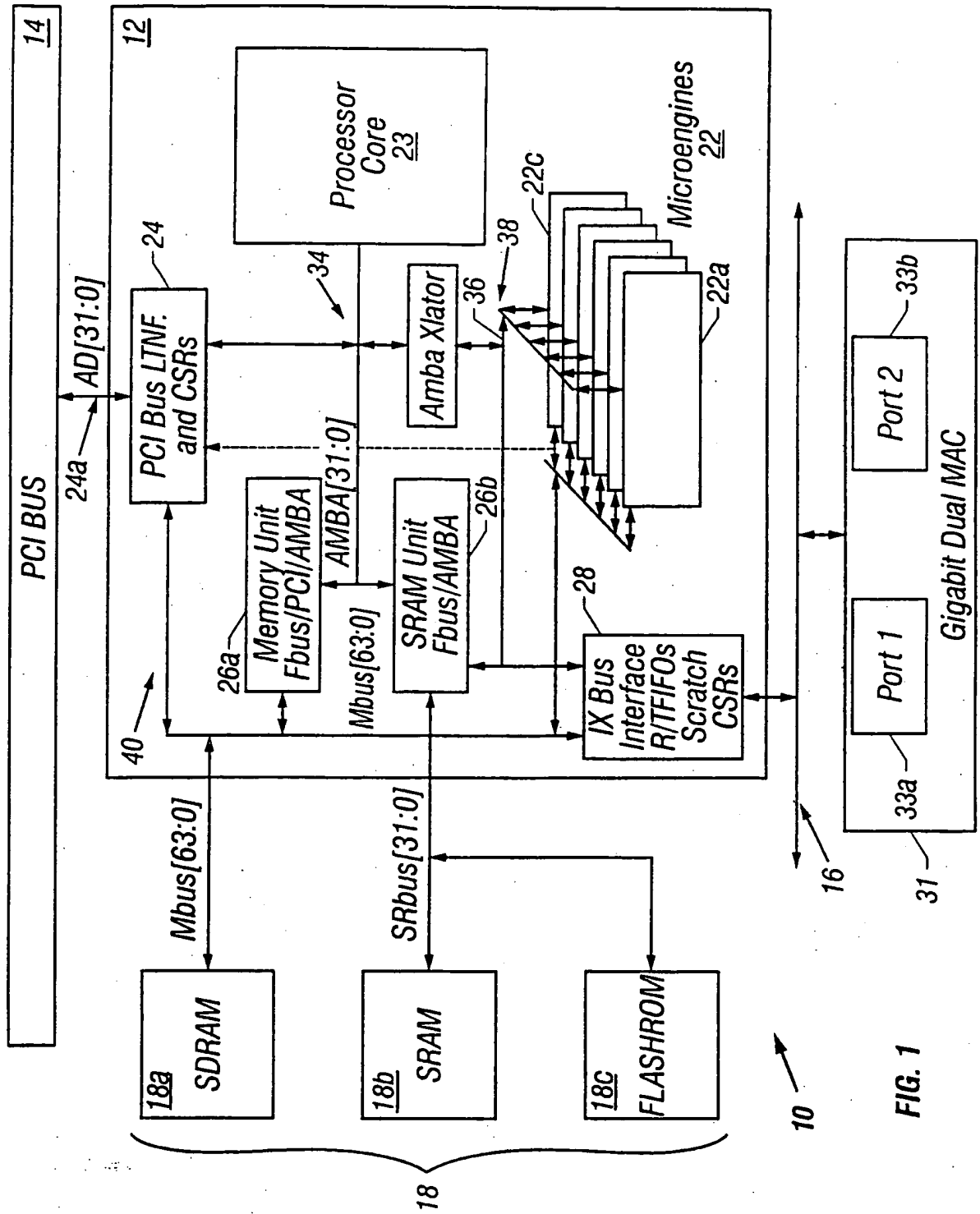


FIG. 1

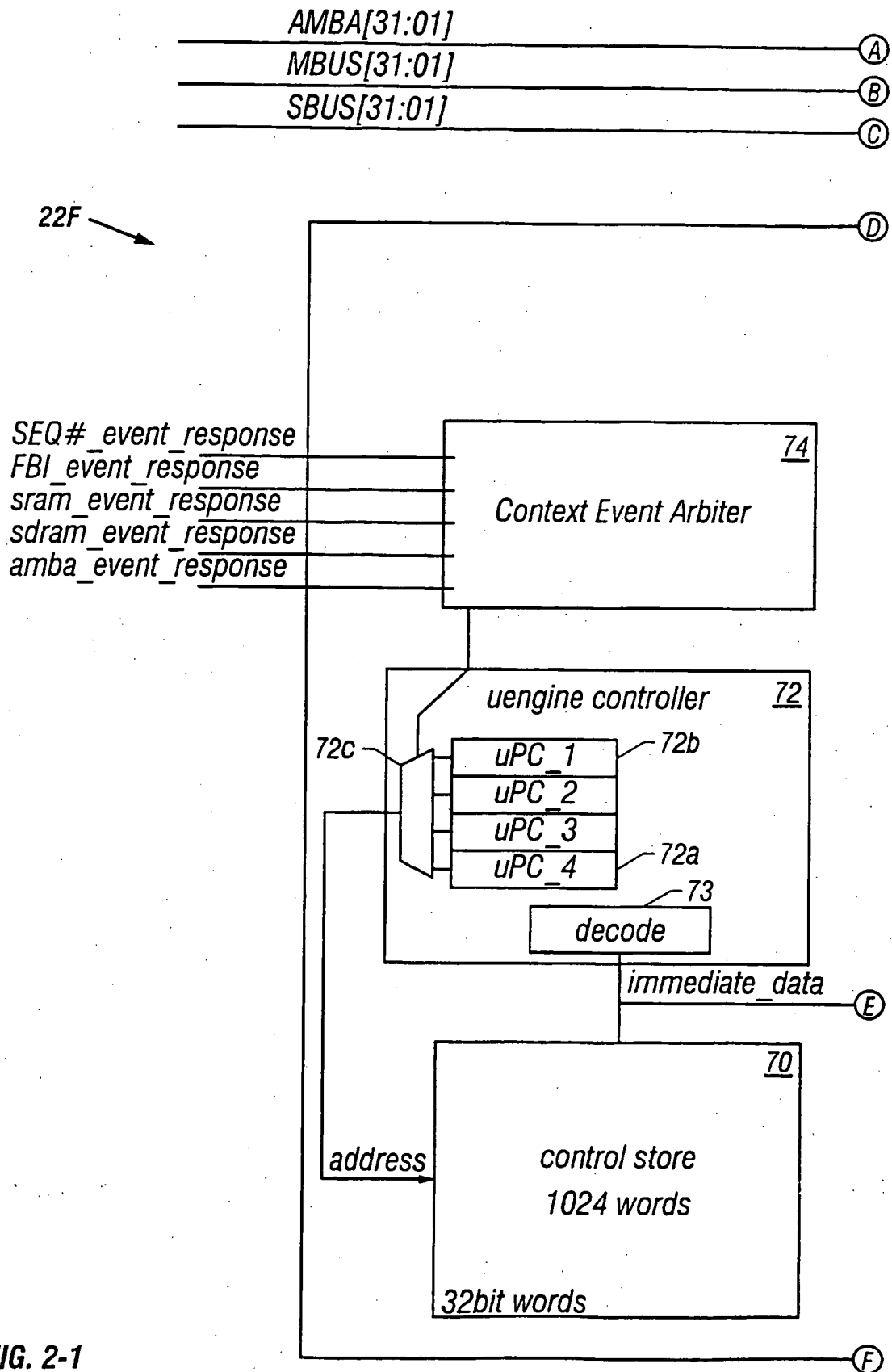


FIG. 2-1

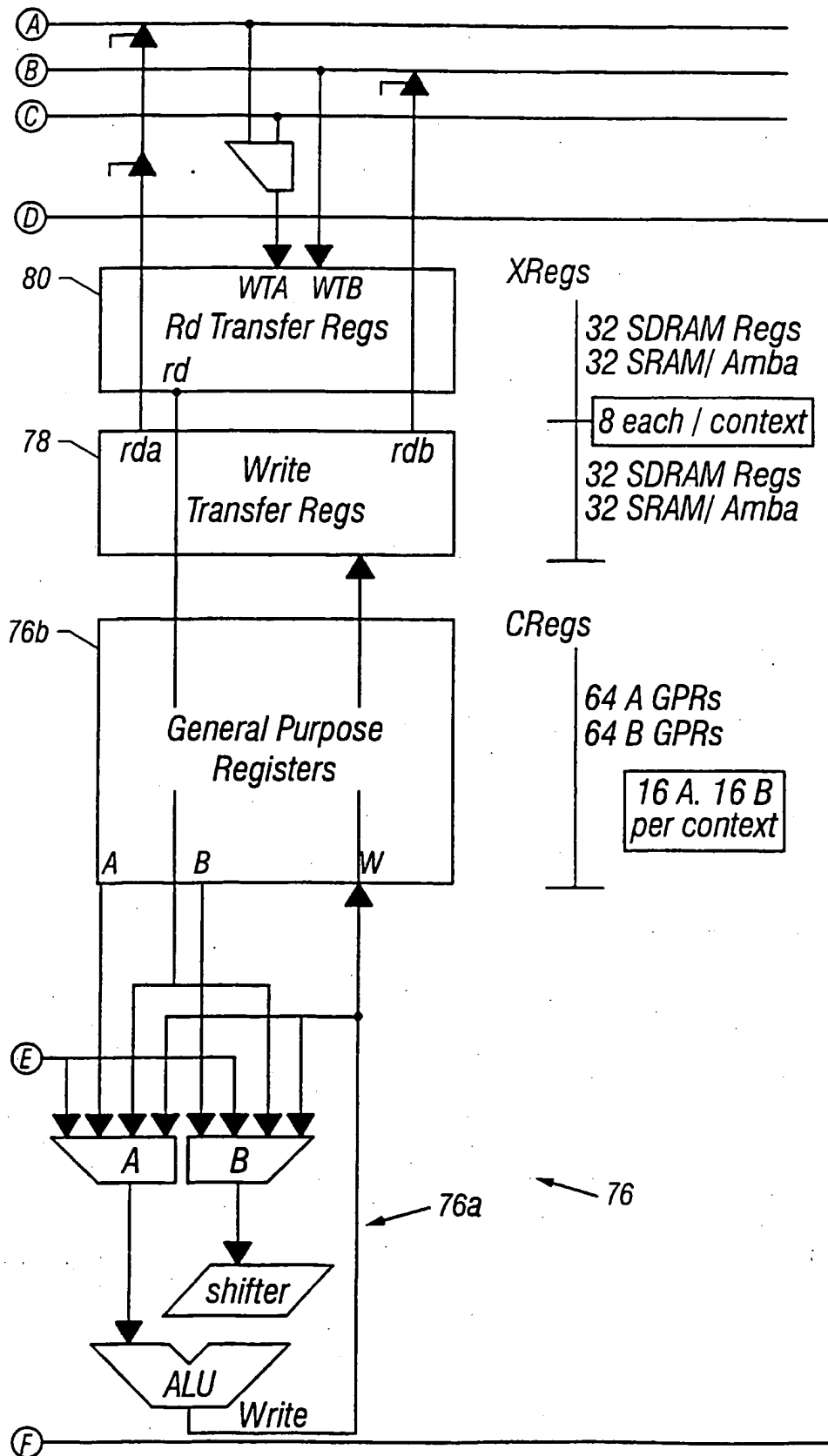


FIG. 2-2



90

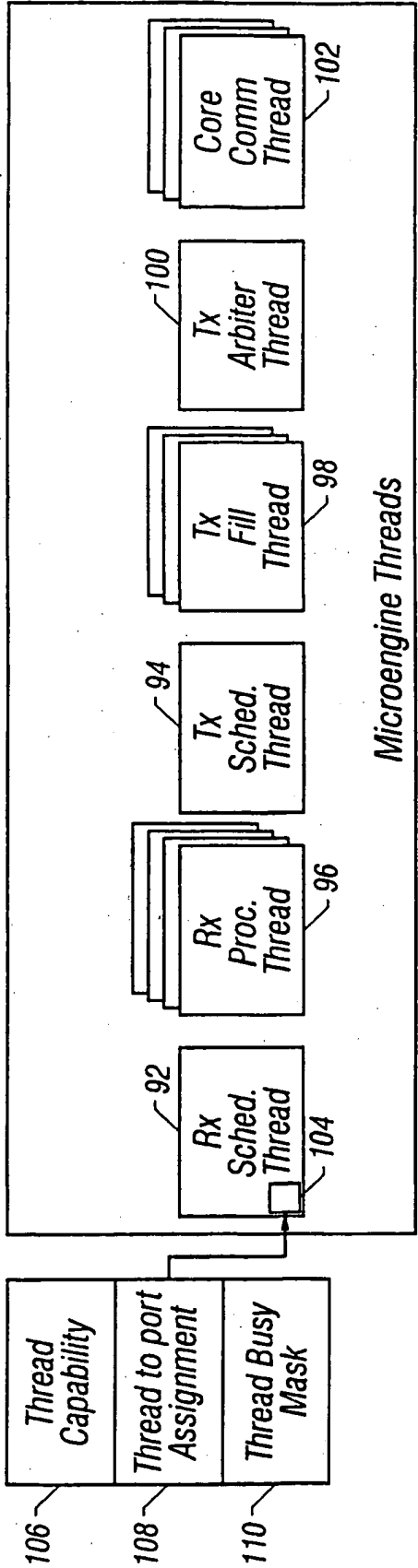


FIG. 3

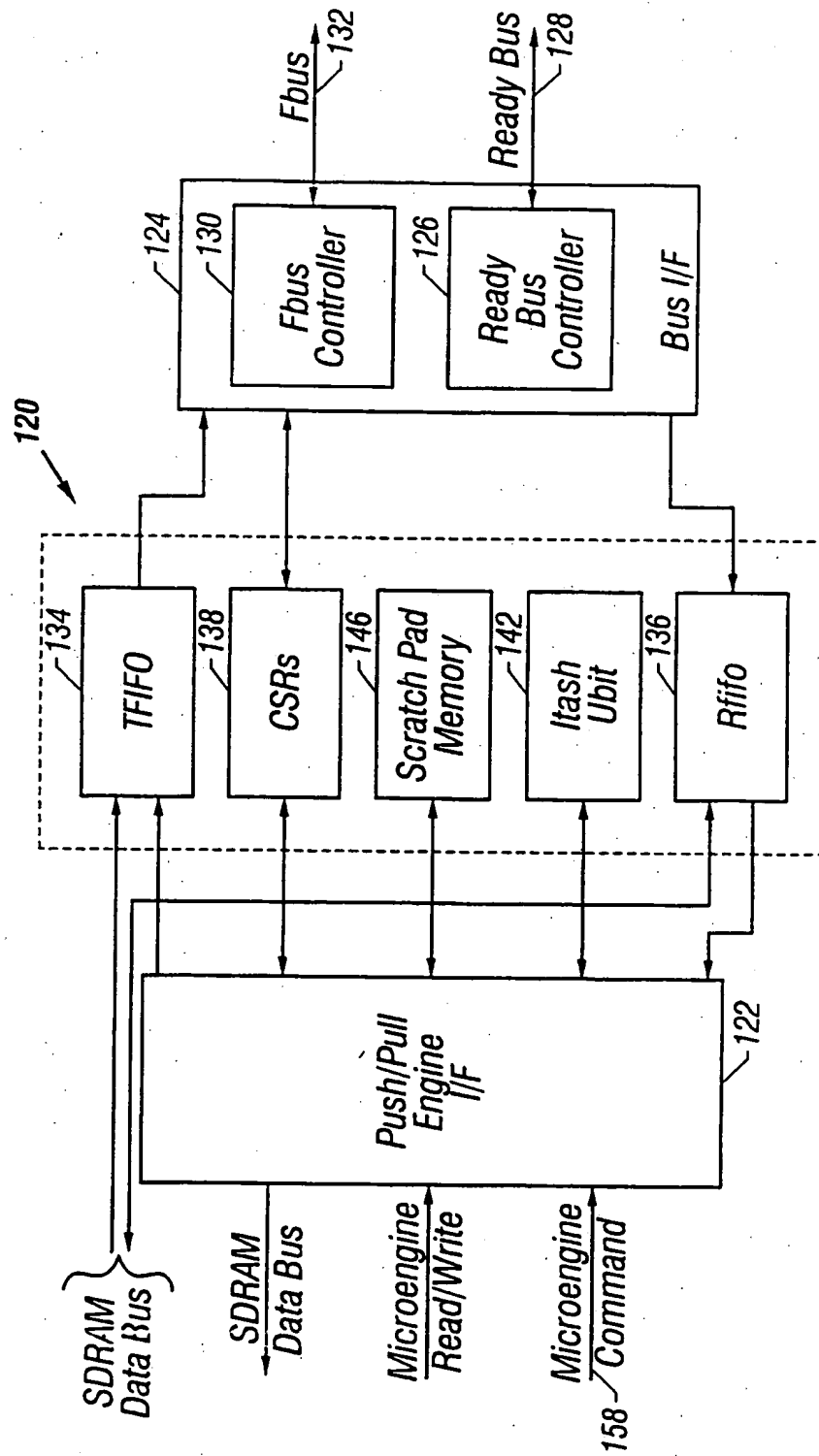
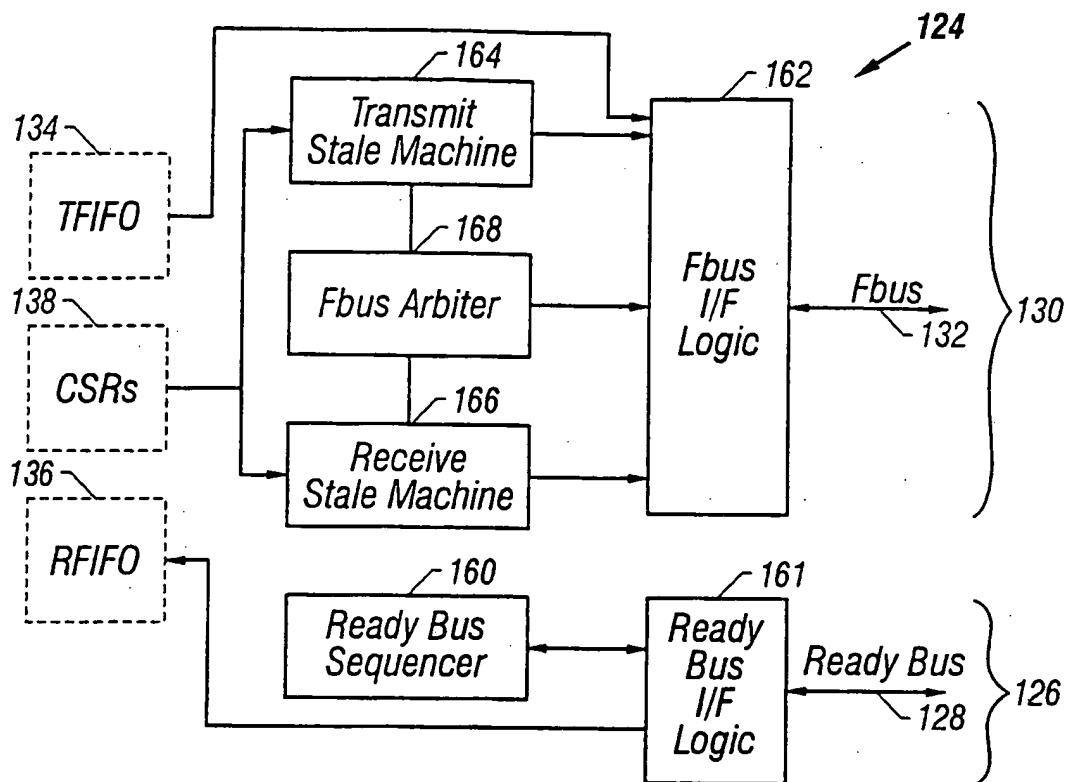
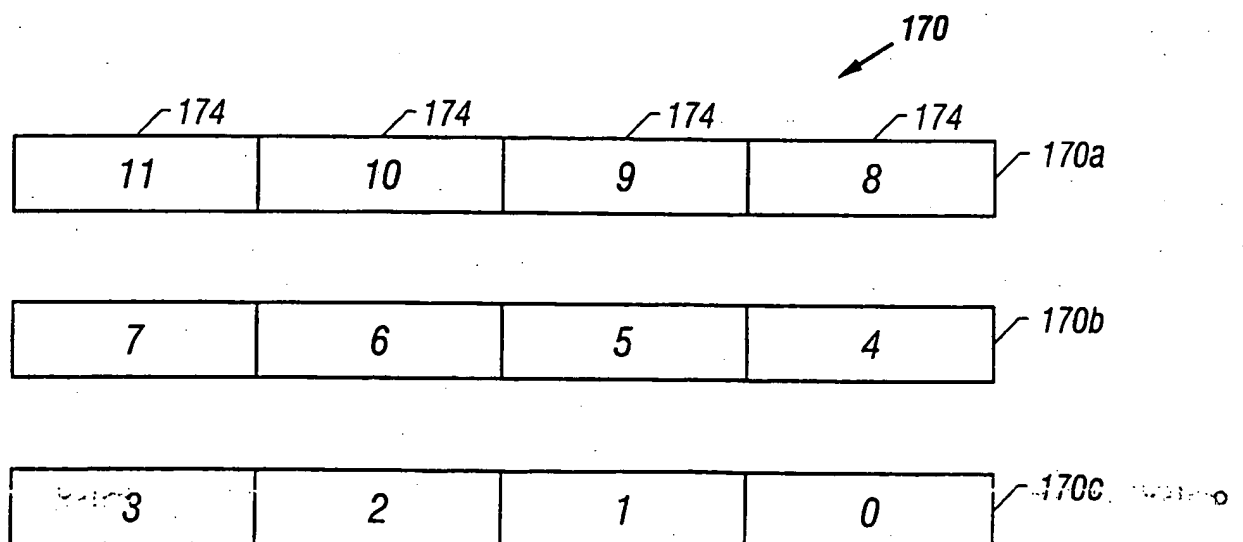


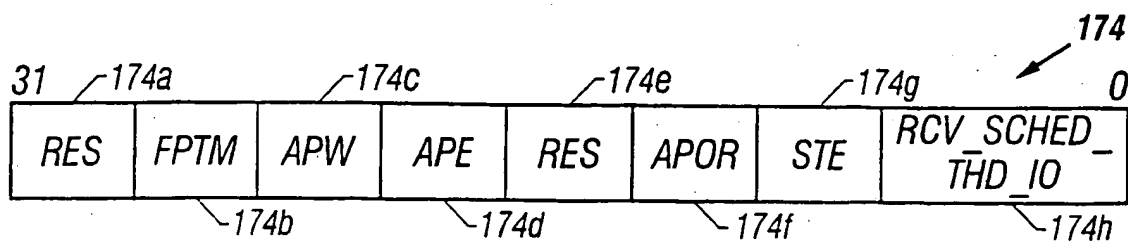
FIG. 4



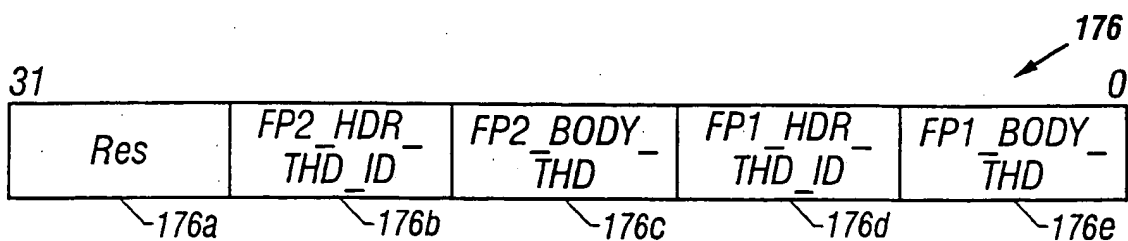
**FIG. 5**



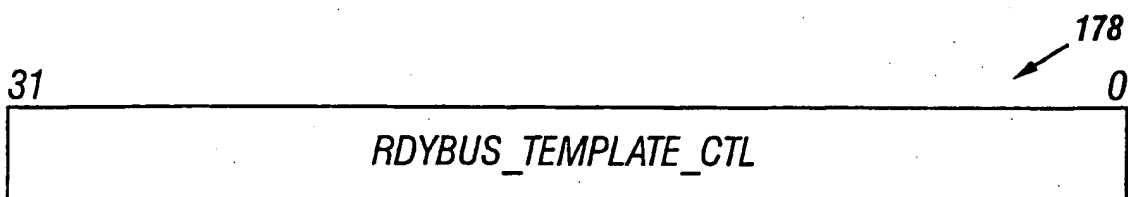
**FIG. 6A**



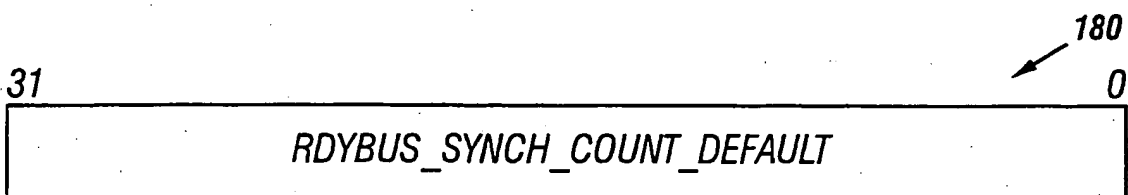
**FIG. 6B**



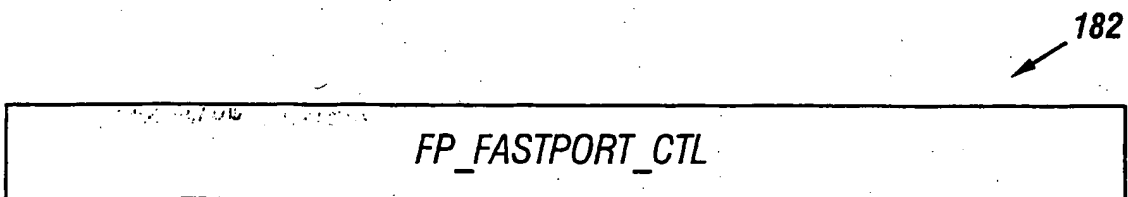
**FIG. 6C**



**FIG. 6D**



**FIG. 6E**



**FIG. 6F**

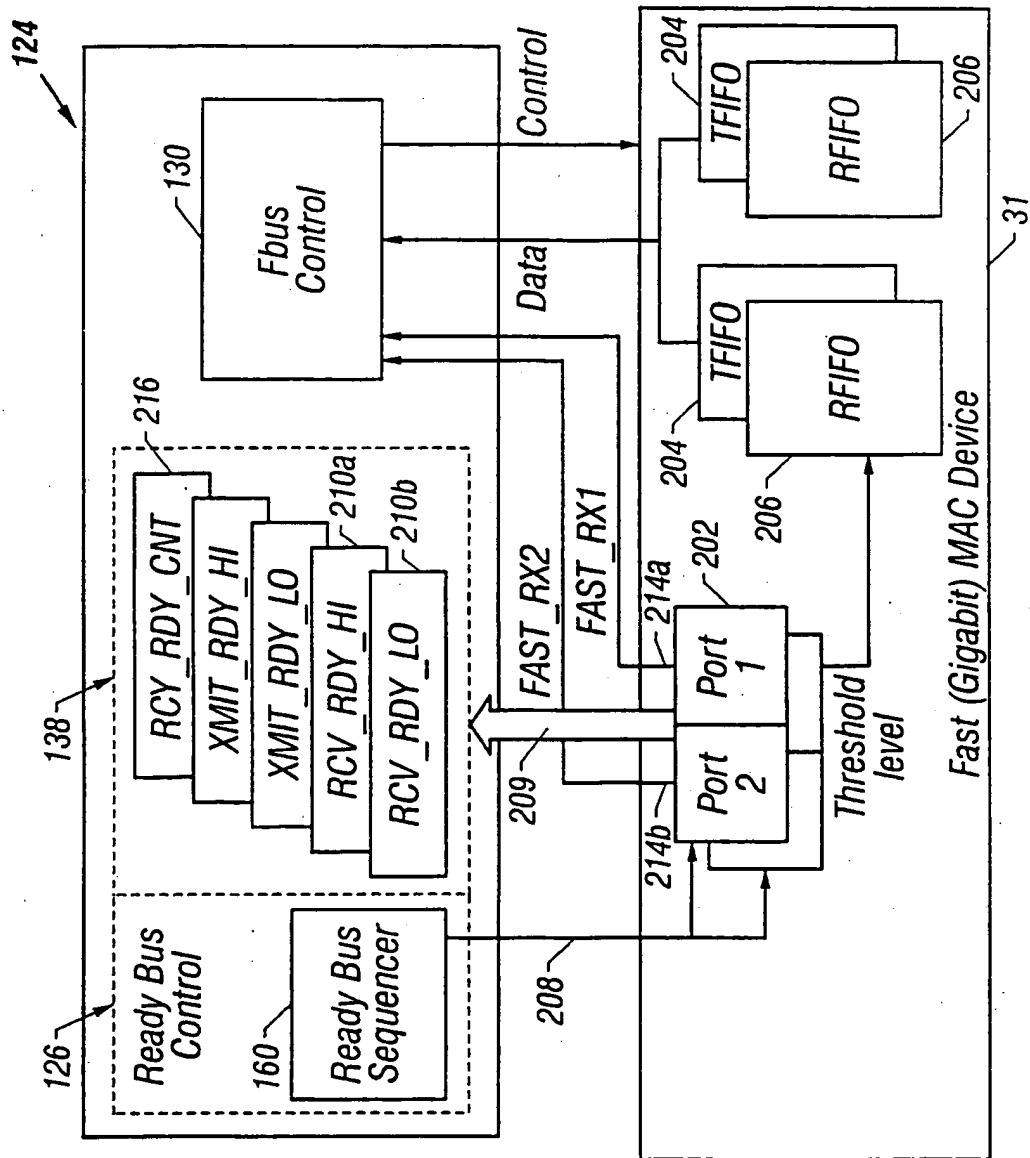


FIG. 7

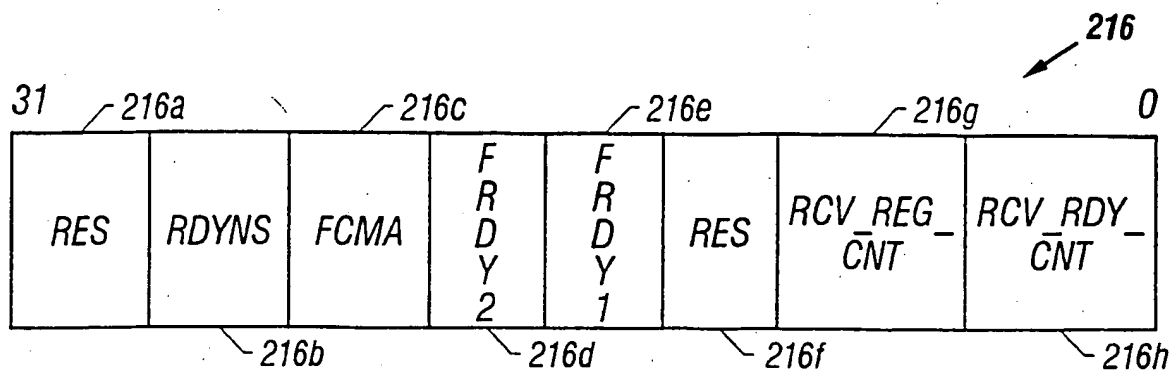


FIG. 8A

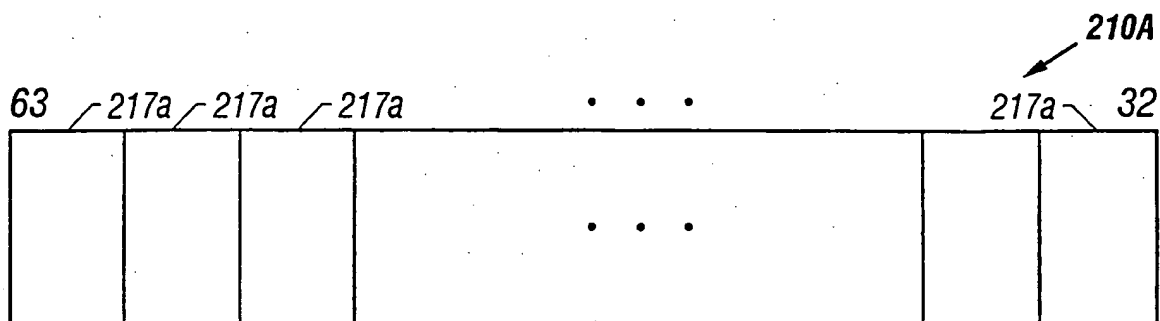


FIG. 8B

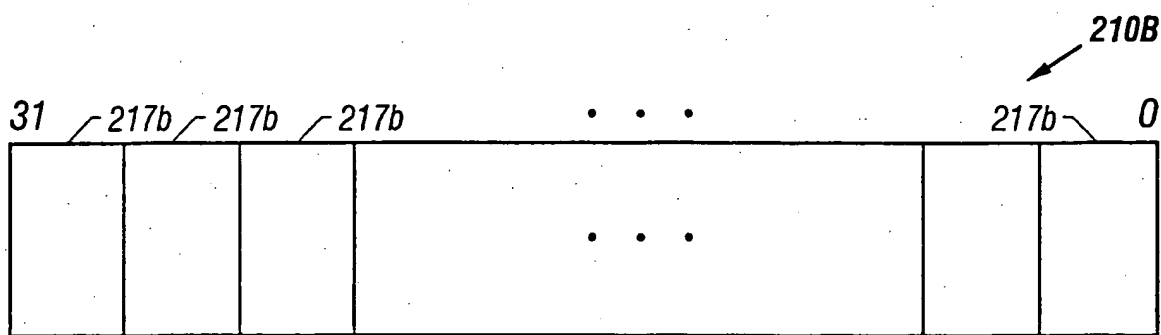


FIG. 8C

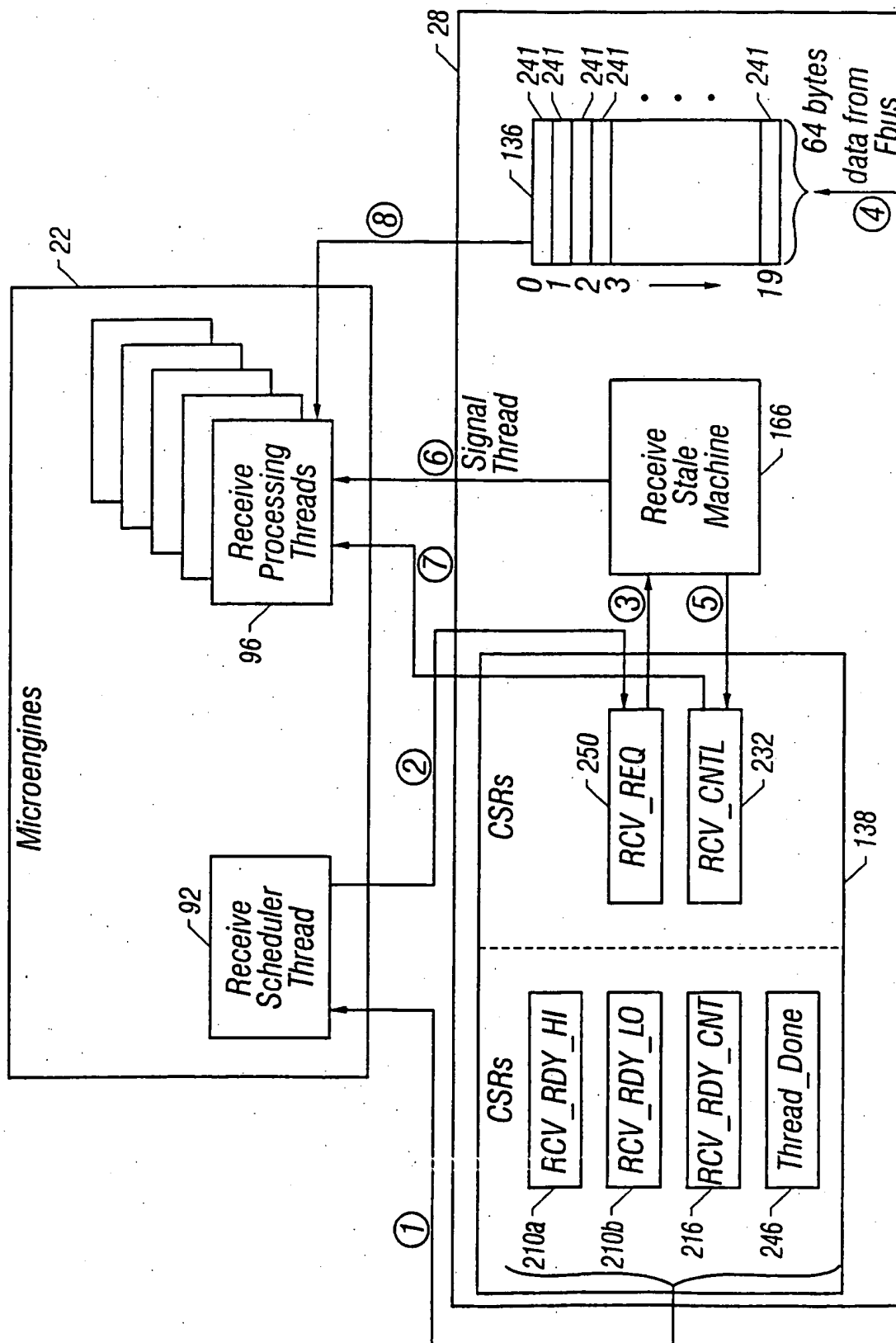


FIG. 9

232

230a	230B	230C	230d	230e	230f	230g	230h	230i	230j	230k	230l	230m
RES	FA	SL	E2	E1	FS	NFE	IGFR	STGRS	TID	RM	RN	
												0
												1

231

FIG. 10A

232

232a	232b	232c	232d	232e	232f	232g	232h	232i	232j	232k	232l
THMSG	MAC- PORT/ THD	SOP SEQ#	RF	RFRR	SE	FE	EFOR	SNOR	Valid Bytes	EOP	SOP
											0
											1
											2
											3

233

233

FIG. 10B



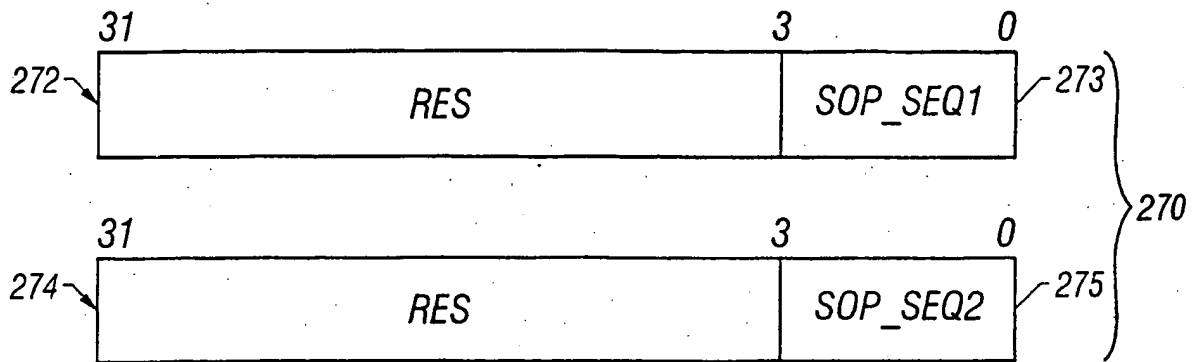


FIG. 11A

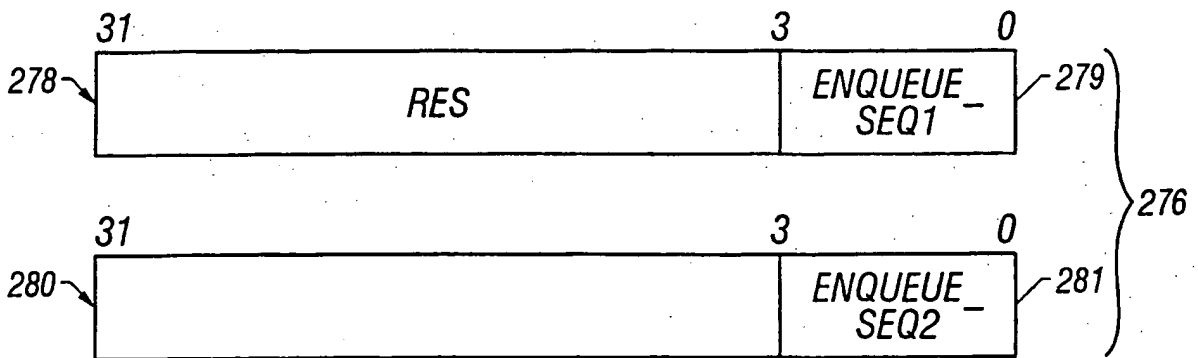


FIG. 11B

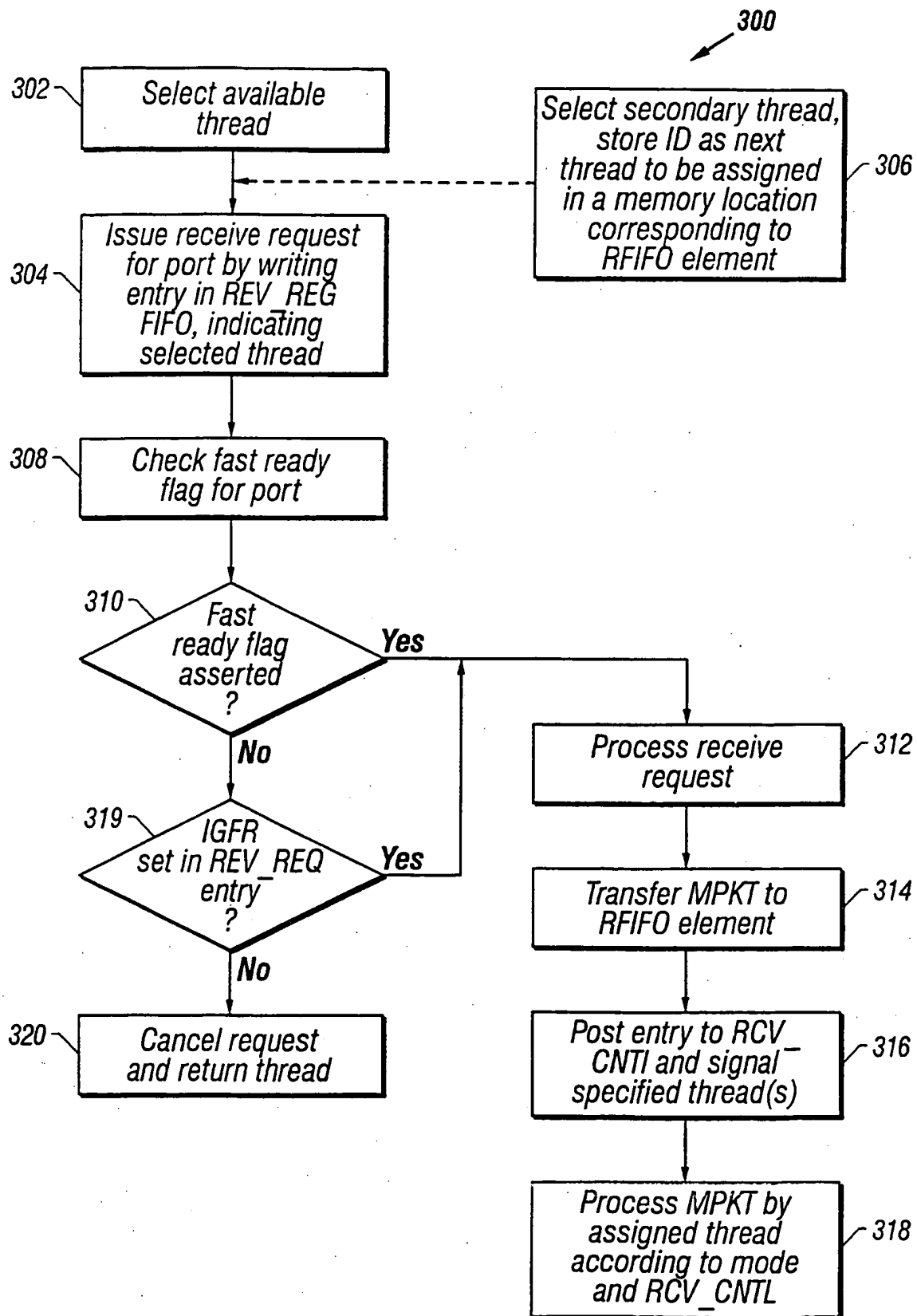


FIG. 12

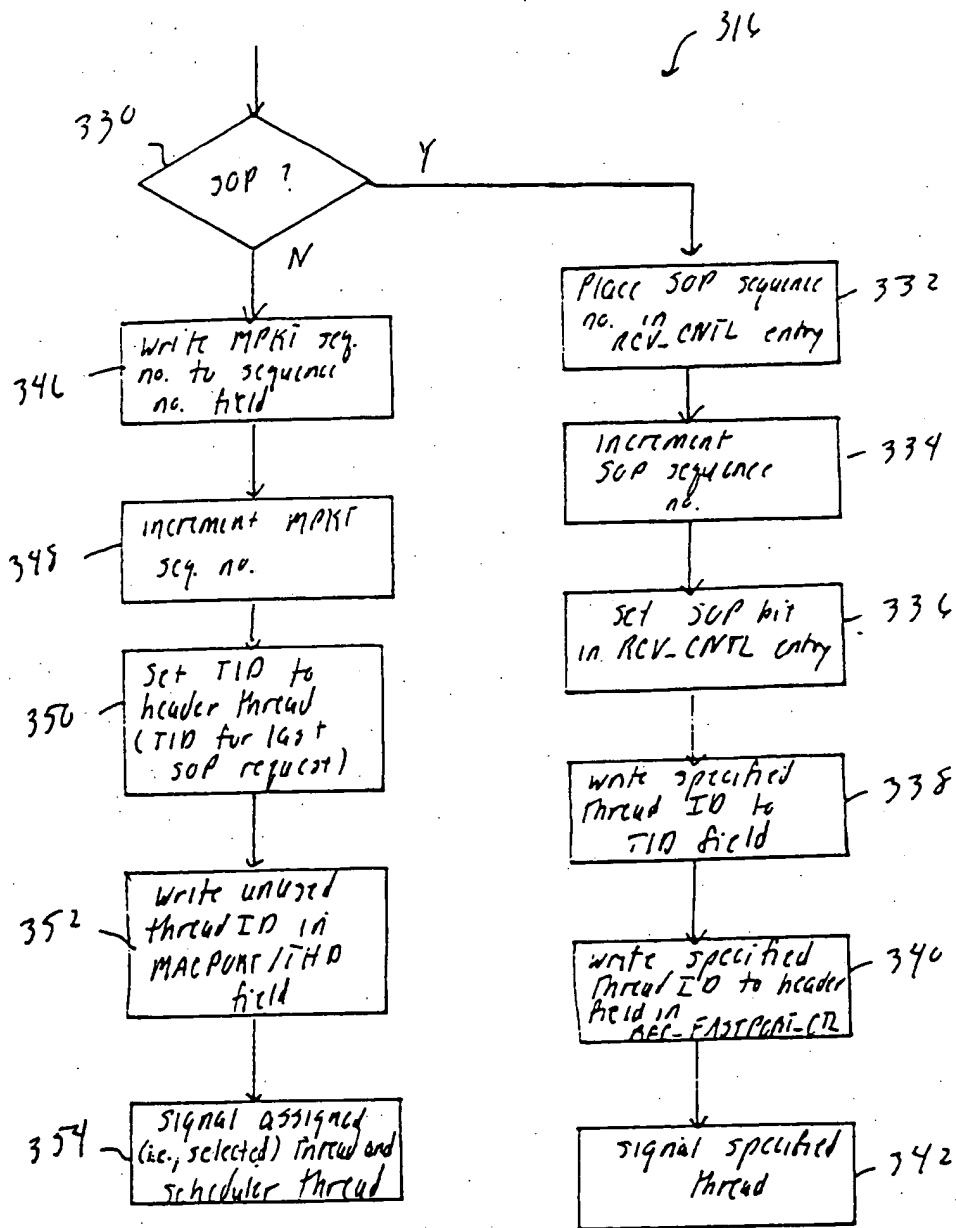


FIG. 13A

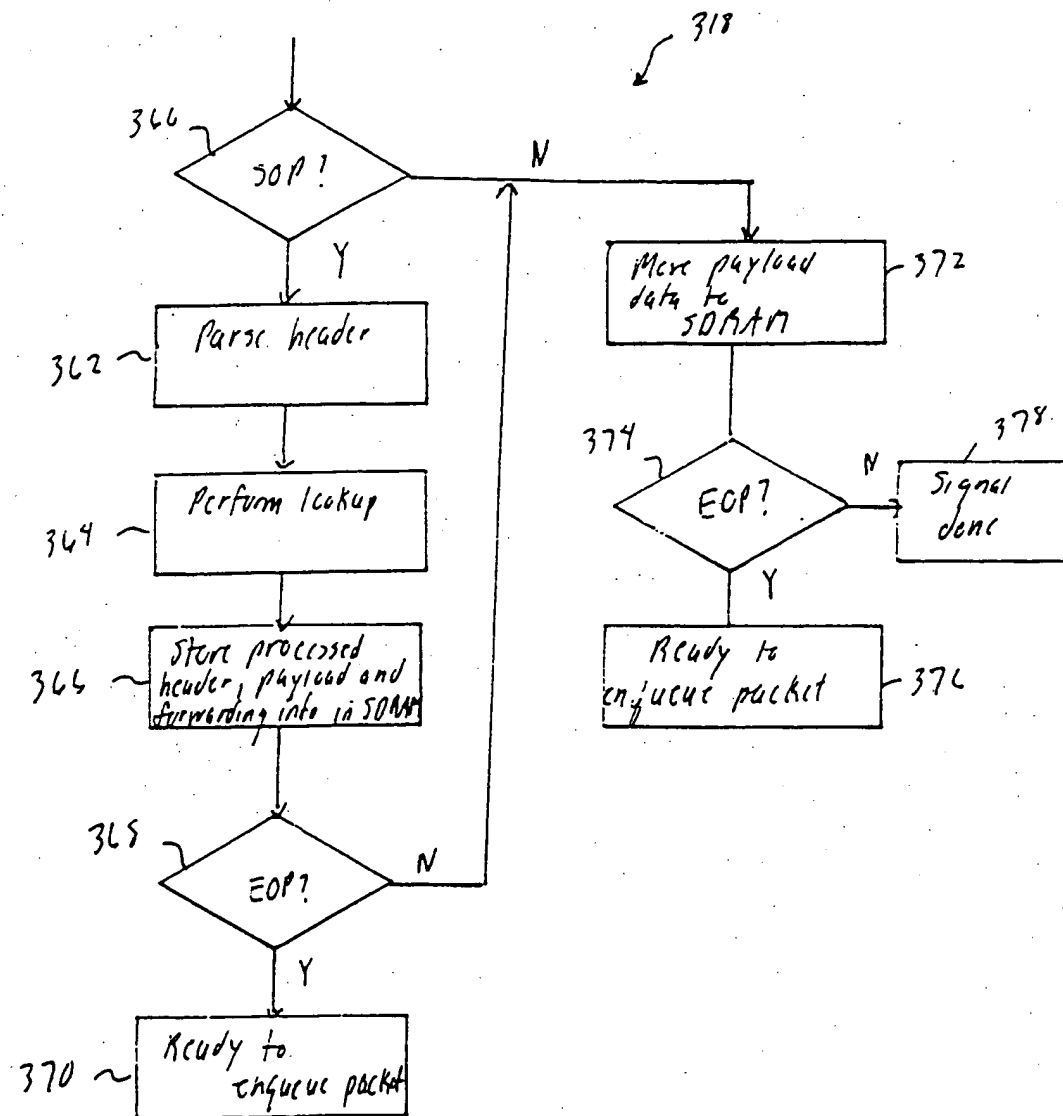


FIG. 13B

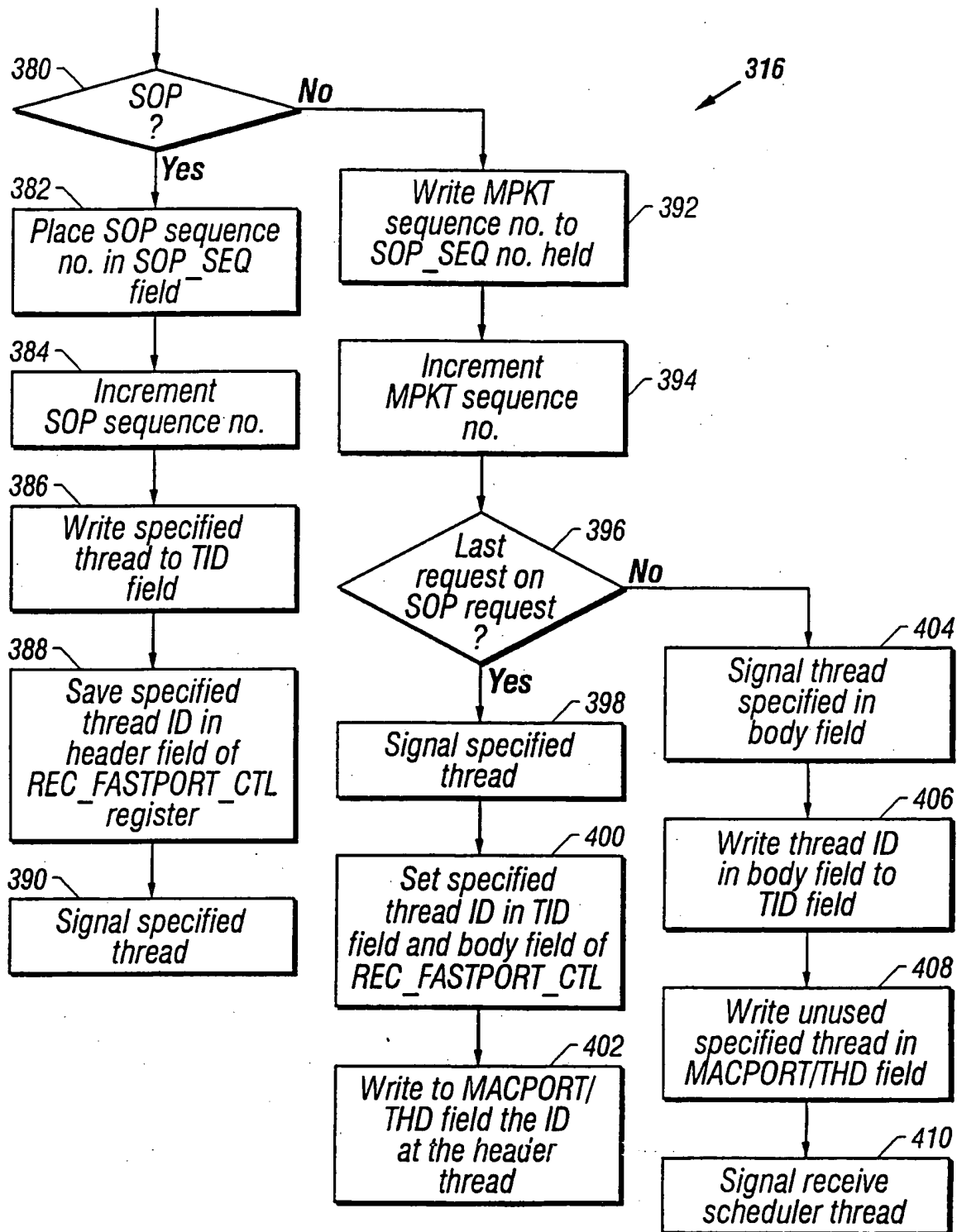


FIG. 14A

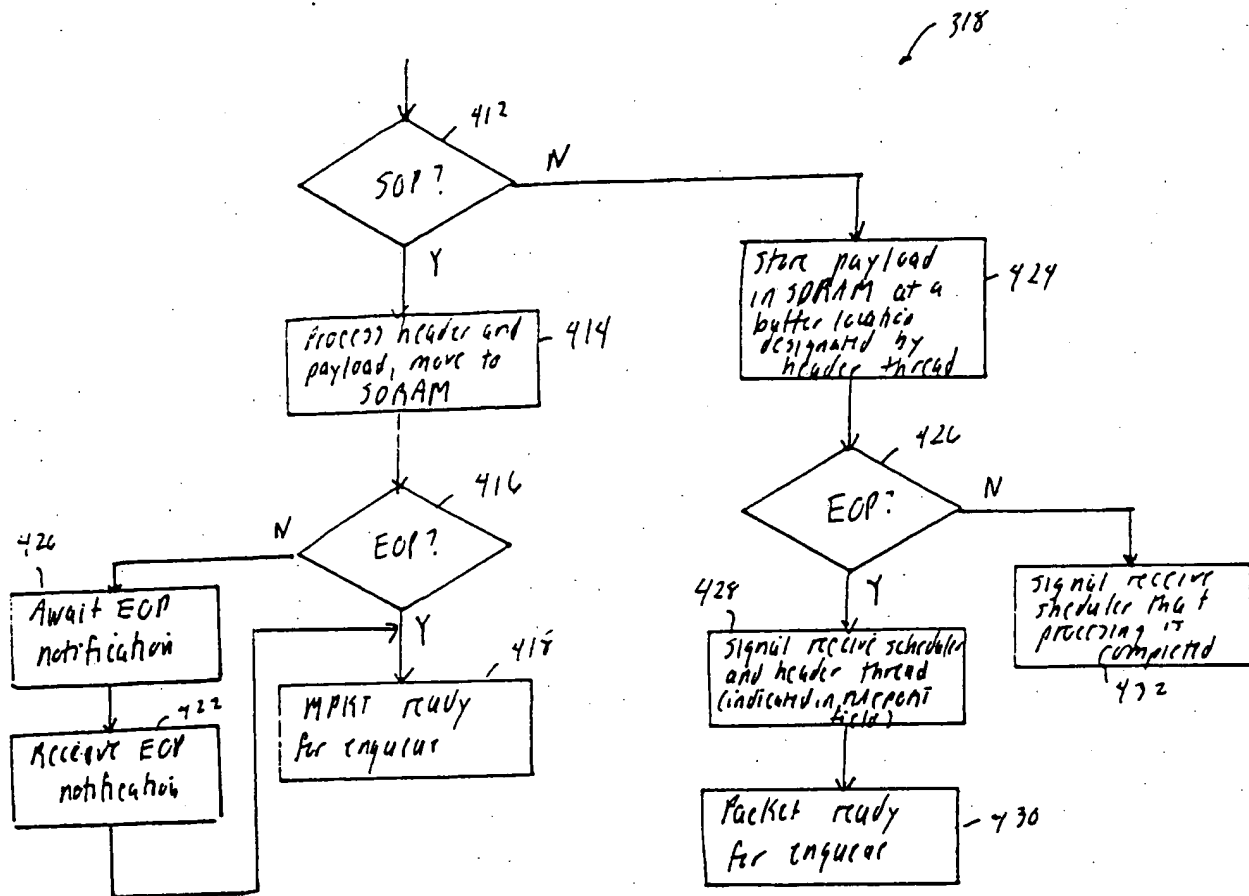


FIG. 14B

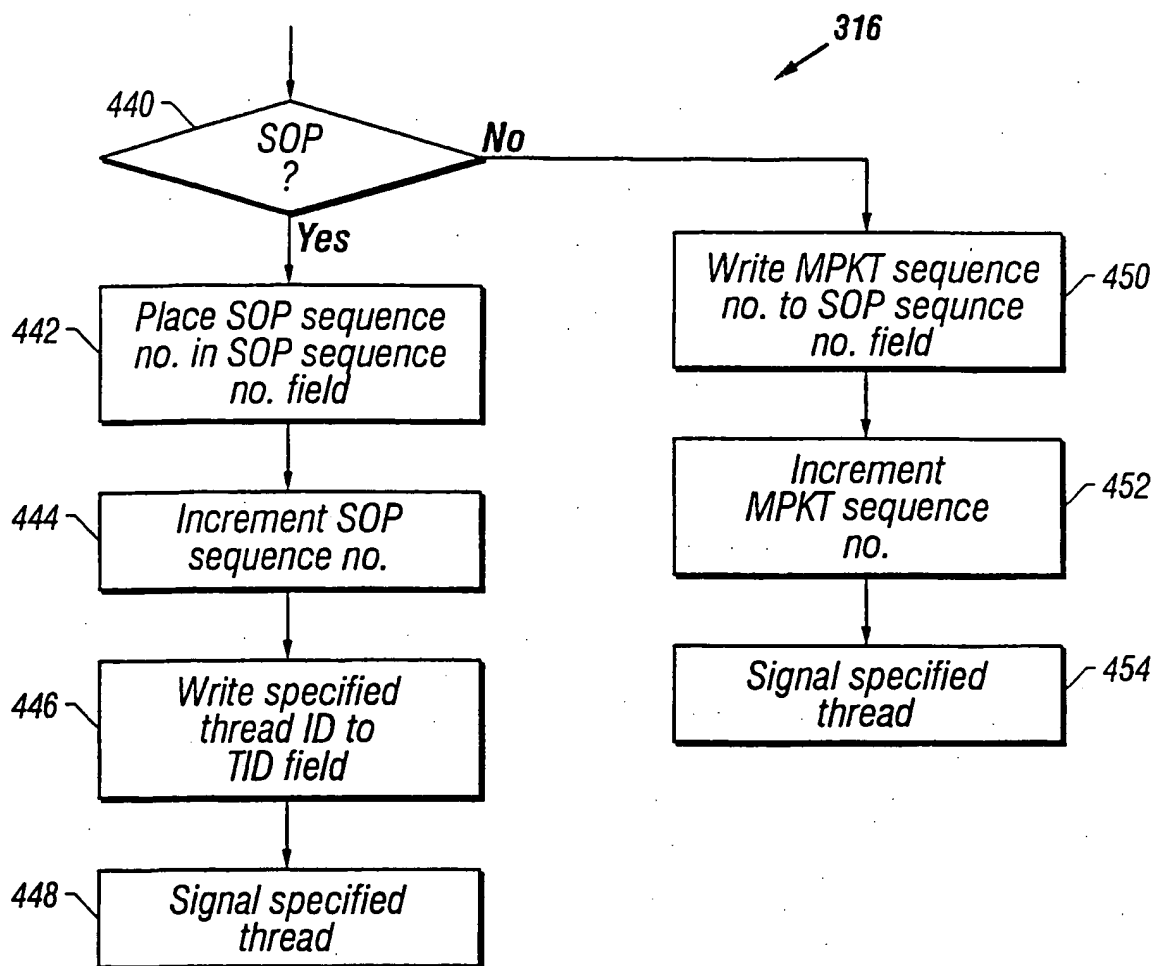


FIG. 15A

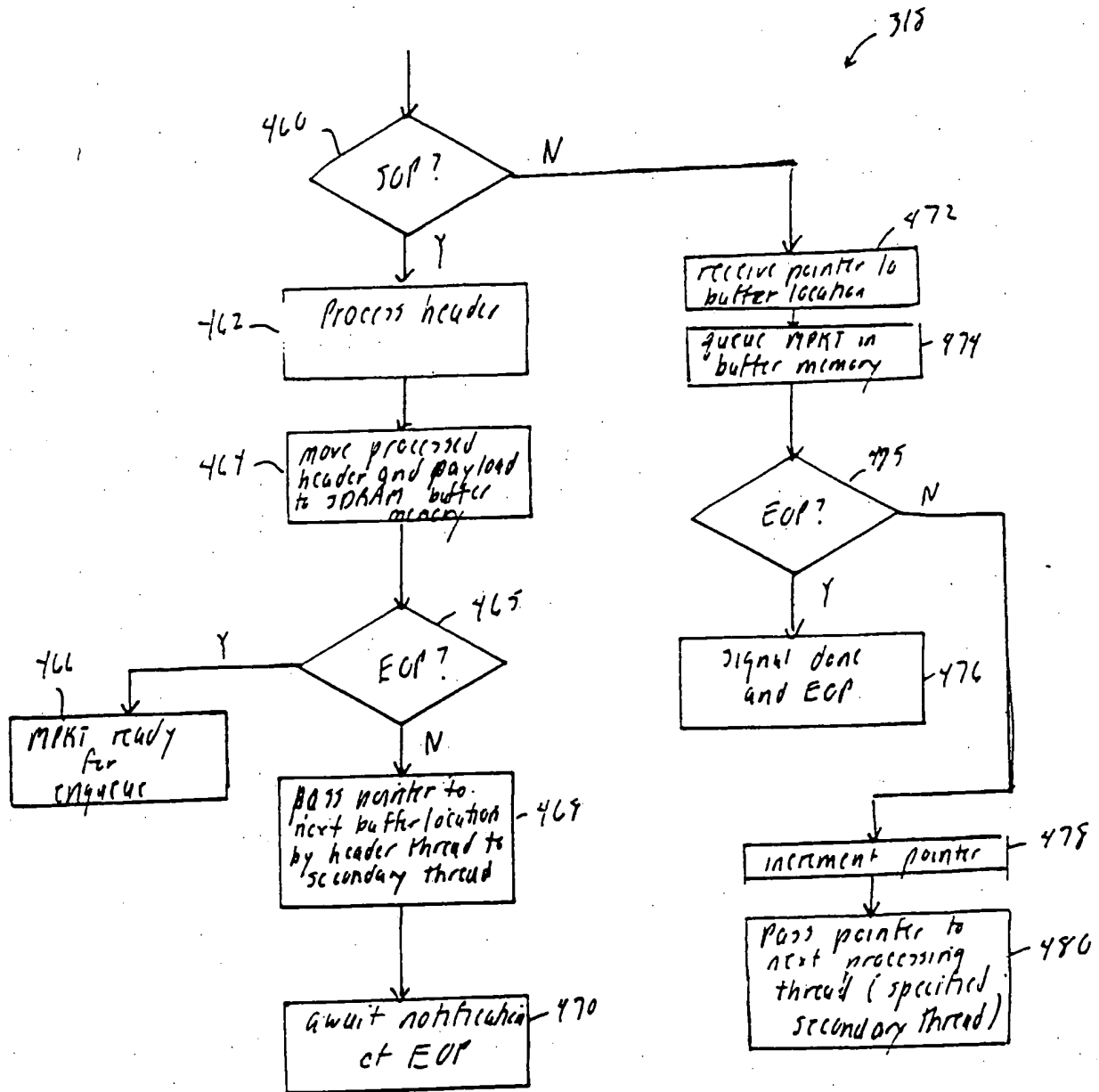


FIG. 15B



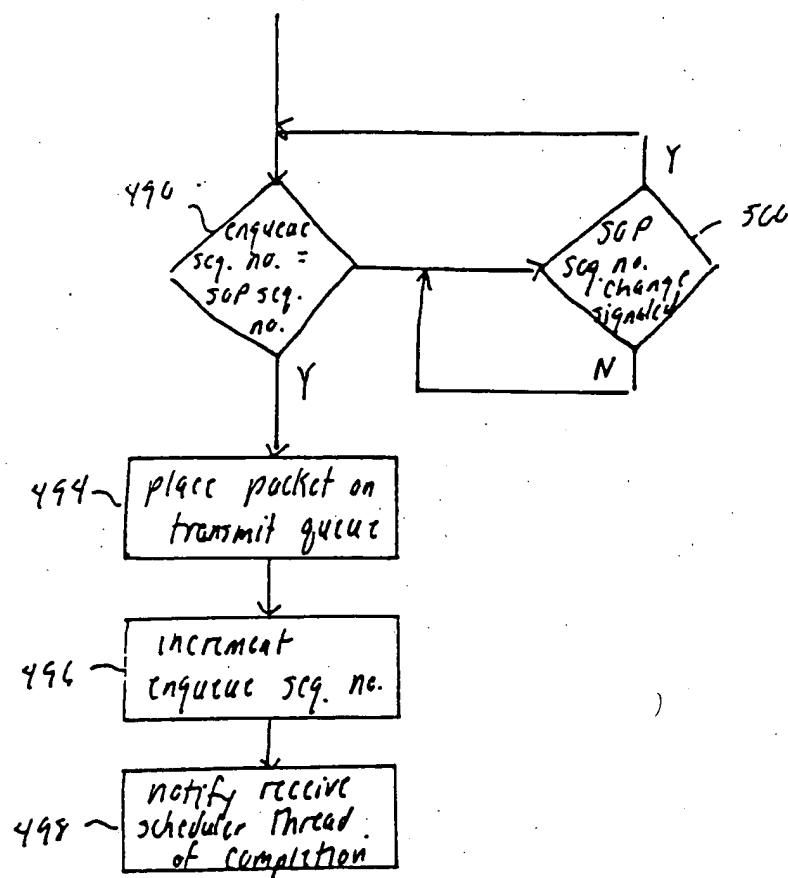


FIG. 16